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(54) Title: FLEXIBLE, MODULAR, COMPACT FIBER OPTIC SWITCH

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(57) Abstract

A fiber optic switch (400) includes a fiber optic switching module (100) that receives and fixes ends (104) of optical fibers (106). The module (100) includes numerous reflective light beam deflectors (172) which may be selected as pairs for coupling a beam of light (108) between a pair of optical fibers (106). The module (100) also produces orientation signals from each deflector (172) which indicate its orientation. A portcard (406) included in the switch (400) supplies drive signals to the module (100) for orienting at least one deflector (172). The portcard (406) also receives the orientation signals produced by that deflector (172) together with coordinates that specify an orientation for the deflector (172). The portcard (406) compares the received coordinates with the orientation signals received from the deflector (172) and adjusts the drive signals supplied to the module (100) to reduce any difference between the received coordinates and the orientation signals. The switch (400) also employs optical alignment to precisely orient pairs of deflectors (172) coupling a beam of light (108) between optical fibers (106).

(57) Abrégé

La présente invention concerne un commutateur à fibres optiques (400) comprenant un module de commutation (100) à fibres optiques qui reçoit et fixe des extrémités (104) de fibres optiques (106). Le module (100) comprend de nombreux déflecteurs (172) de rayons lumineux de réflexion qui peuvent être choisis par paires afin de coupler un rayon lumineux (108) entre deux fibres optiques (106). Le module (100) permet aussi de produire des signaux d'orientation à partir de chaque déflecteur (172) indiquant ainsi son orientation. Une carte-accès (406) comprise dans le commutateur (400) délivre des signaux de commande au module (100) afin d'orienter au moins un déflecteur (172). La carte-accès (406) reçoit aussi les signaux d'orientation produits par ce déflecteur (172) accompagnés des coordonnées qui spécifient une orientation du déflecteur (172). La carte-accès (406) compare les coordonnées reçues avec les signaux d'orientation provenant du déflecteur (172) et ajuste les signaux de commande délivrés au module (100) afin de réduire toute différence entre les coordonnées reçues et les signaux d'orientation. Le commutateur (400) utilise aussi un alignement optique de manière à orienter avec précision des paires de déflecteurs (172) qui couplent un rayon lumineux (108) entre deux fibres optiques (106).

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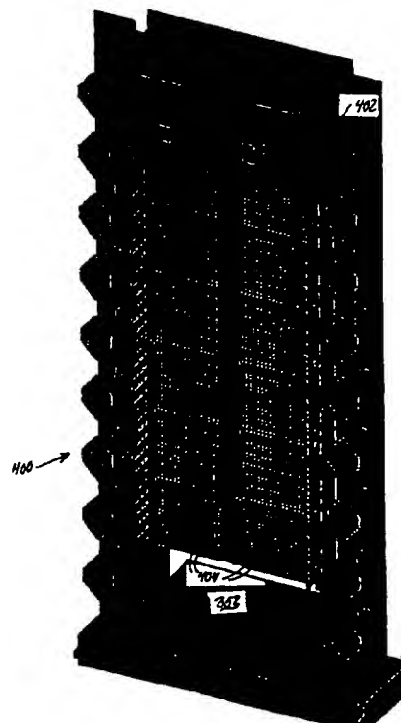
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(54) Title: FLEXIBLE, MODULAR, COMPACT FIBER OPTIC SWITCH

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FLEXIBLE, MODULAR, COMPACT
FIBER OPTIC SWITCH

Technical Field

5 The present invention relates generally to the technical field of fiber optics, and, more particularly, to free-space, reflective N×N fiber optic switches.

Background Art

10 A dramatic increase in telecommunications during recent years, which may be attributed largely to increasing Internet
15 communications, has required rapid introduction and commercial adoption of innovations in fiber optic telephonic communication systems. For example, recently fiber optic telecommunication
20 systems have been introduced and are being installed for transmitting digital telecommunications concurrently on 4, 16,
25 32, 64 or 128 different wavelengths of light that propagate along a single optical fiber. While multi-wavelength fiber optic telecommunications dramatically increases the bandwidth of a
30 single optical fiber, that bandwidth increase is available only at both ends of the optical fiber, e.g. between two cities. When light transmitted into one end of the optical fiber arrives at the other end of the optical fiber, there presently does not
35 exist a flexible, modular, compact, N×N fiber optic switch which permits automatically forwarding light received at one end of the
40 optical fiber onto a selected one of several different optical fibers which will carry the light onto yet other destinations.

45 Historically, when telecommunications were transmitted by electrical signals via pairs copper wires, at one time a human
50 being called a telephone operator sat at a manually operated switchboard and physically connected an incoming telephone call, received on one pair of copper wires, that were attached to a plug, to another pair of copper wires, that were attached to a socket, to complete the telephone circuit. The telephone
55 operator's task of manually interconnecting pairs of wires from two (2) telephones to establish the telephone circuit was first replaced by an electro-mechanical device, called a crossbar switch, which automated the operator's manual task in response

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5 to telephone dialing signals. During the past forty years, the electro-mechanical crossbar switch for electrical telecommunications has been replaced by electronic switching systems.

10 Presently, switches for fiber optic telephonic communications exist which perform functions for fiber optic telephonic communications analogous to or the same as the crossbar switch and electronic switching systems perform for electrical telephonic communications. However, the presently available fiber optic switches are far from ideal. That is, existing fiber optic
15 telecommunications technology lacks a switch that performs the same function for optical telecommunications as that performed by electronic switching systems for large numbers of optical
20 fibers.

One approach used in providing a 256x256 switch for fiber
25 optic telecommunications first converts light received from a incoming optical fiber into an electrical signal, then transmits the electrical signal through an electronic switching network. The output signal from that electronic switching network is then used to generate a second beam of light that then passes into an
30 output optical fiber. As those familiar with electronics and optical fiber telecommunications recognize, the preceding approach for providing a 256x256 fiber optic switch is physically very large, requires electrical circuits which process extremely high-speed electronic signals, and is very expensive.

35 Attempting to avoid complex electronic circuits and conversions between light and electronic signals, various proposals exist for assembling a fiber optic switch that directly couples a beam of light from one optical fiber into another
40 optical fiber. One early attempt to provide a fiber optic switch, analogous to the electrical crossbar switch, mimics with machinery the actions of a telephone operator only with optical fibers rather than for pairs of copper wires. United States
45 Patent No. 4,886,335 entitled "Optical Fiber Switch System" that issued December 12, 1989, includes a conveyor that moves ferrules
35 attached to ends of optical fibers. The conveyer moves the ferrule to a selected adapter and plugs the ferrule into a coupler/decoupler included in the adapter. After the ferrule is
50 plugged into the coupler/decoupler, light passes between the

55

5 optical fiber carried in the ferrule and an optical fiber secured in the adapter.

10 United States Patent no. 5,864,463 entitled "Miniature 1xN Electromechanical Optical Switch And Variable Attenuator" which
5 issued January 26, 1999, ("the '463 patent") describes another mechanical system for selectively coupling light between one optical fiber and one of a number of optical fibers. This patent
15 discloses selectively coupling light between one optical fiber and a selected optical fiber by mechanically moving an end of one
10 optical fiber along a linear array of ends of the other optical fibers. The 1xN switch uses a mechanical actuator to coarsely align the end of the one optical fiber to a selected one of the
20 other optical fibers within 10 μ m. The 1xN switch, using light reflected back into the moving optical fiber from the immediately adjacent end of the selected optical fiber, then more precisely
15 aligns the end of the input optical fiber to the output optical fiber. United States Patent no. 5,699,463 entitled "Mechanical Fiber Optic Switch" that issued December 16, 1997, also aligns
25 an end of one optical fiber to one of several other optical fibers assembled as a linear array, but interposes a lens between
30 ends of the two optical fibers.

United States Patent No. 5,524,153 entitled "Optical Fiber Switching System And Method Of Using Same" that issued June 4,
35 1996, ("the '153 patent") disposes two (2) optically opposed
25 groups of optical fiber switching units adjacent to each other. Each switching unit is capable of aligning any one of its optical fibers with any one of the optical fibers of the optically opposed group of switching units. Within the switching unit, an
40 end of each optical fiber is positioned adjacent to a beamforming
30 lens, and is received by a two-axis piezoelectric bender. The two-axis piezoelectric bender is capable of bending the fiber so light emitted from the fiber points at a specific optical fiber
45 in the optically opposed group of switching units. Pulsed light generated by radiation emitting devices ("REDs") associated with
35 each optical fiber pass from the fiber to the selected optical fiber in the opposing group. The pulsed light from the RED
50 received by the selected optical fiber in the opposing group is processed to provide a signal that is fed back to the piezoelec-

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5 tric bender for pointing light from the optical fiber directly
at the selected optical fiber.

10 Rather than mechanically effecting alignment of a beam of
light from one optical fiber to another optical fiber either by
5 translating or by bending one or both optical fibers, optical
switches have been proposed that employ micromachined moving
mirror arrays to selectively couple light emitted from an input
15 optical fiber to an output optical fiber. Papers presented at
OFC/IIOC '99, February 21-26, 1999, describe elements that could
20 be used to fabricate a three (3) stage fully non-blocking fiber
optic switch, depicted graphically in FIG. 1. This fiber optic
switch employs moving mirror arrays in which each polysilicon
25 mirror can selectively reflect light at a 90° angle. In this
proposed fiber optic switch, rows of relatively small 32×64
15 optical switching arrays 52a_i (i = 1, 2 . . . 32) and 52b_k
(k = 1, 2 . . . 32) receive light from or transmit light to
25 thirty-two (32) input or output optical fibers 54a_n and 54b_n.
Thirty-two groups of sixty-four (64) optical fibers 56a_{i,m} and
56b_{i,m} carry light between each of the 32×64 optical switching
20 arrays 52a_i and 52b_k and one of sixty-four 32×32 optical switch-
ing arrays 58_j (j = 1, 2 . . . 64).

30 The complexity of the fiber optic switch illustrated in FIG.
1 is readily apparent. For example, a 1024×1024 fiber optic
switch assembled in accordance with that proposal requires 4096
35 individual optical fibers for interconnecting between the 32×64
optical switching arrays 52a_i and 52b_k and the 32×32 optical
switching arrays 58_j. Moreover, the 32×64 optical switching
arrays 52a_i and 52b_k and 32×32 optical switching arrays 58_j
40 require a total of 196,608 micromachined mirrors.

30 The polysilicon mirrors proposed for the fiber optic switch
illustrated in FIG. 1 are curved rather than optically flat.
Furthermore, while those mirrors possess adequate thermal
45 dissipation for switching a single 0.3 mW wavelength of light and
perhaps even a few such wavelengths, they are incapable of
35 switching even ten (10) or twenty (20) such wavelengths.
However, as described above fiber optic telecommunications
50 systems are already transmitting many more than twenty (20)
wavelengths over a single optical fiber, and, if not already,

5 will soon be transmitting hundreds of wavelengths. If instead
of a single wavelength of light one optical fiber carries 300
different wavelengths of light each having a power of 0.3 mW,
10 then 100 mW of power impinges upon the polysilicon mirror
5 proposed for this fiber optic switch. If the polysilicon mirror
reflects 98.5% of that light, the mirror must absorb substantial-
ly all of the remainder, i.e. 1.5 mW of power. Absorption of 1.5
15 mW of power would likely heat the thermally non-conductive
polysilicon mirror to unacceptable temperatures which would
10 further degrade mirror flatness.

20 Disclosure of Invention

The present invention provides a fiber optic switch capable
of concurrently coupling incoming beams of light carried on more
15 than 1,000 individual optical fibers to more than 1,000 outgoing
optical fibers.

25 An object of the present invention is to provide a simpler
fiber optic switch that is capable of switching among a large
number of incoming and outgoing beams of light carried on optical
20 fibers.

30 Another object of the present invention is to provide an
efficient fiber optic switch that is capable of switching among
a large number of incoming and outgoing beams of light carried
on optical fibers.

35 25 Another object of the present invention is to provide a
fiber optic switch which has low cross-talk between communication
channels.

40 Another object of the present invention is to provide a
fiber optic switch which has low cross-talk between communication
30 channels during switching thereof.

Another object of the present invention is to provide an
highly reliable fiber optic switch.

45 Another object of the present invention is to provide a
fiber optic switch that does not exhibit dispersion.

35 Another object of the present invention is to provide a
fiber optic switch that is not polarization dependent.

50 Another object of the present invention is to provide a
fiber optic switch that is fully transparent.

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Another object of the present invention is to provide a fiber optic switch that does not limit the bitrate of fiber optic telecommunications passing through the switch.

Briefly the present invention is a fiber optic switch that includes a fiber optic switching module that receives and fixes ends of optical fibers. In addition to receiving and fixing ends of optical fibers, the fiber optic switching module includes a plurality of reflective light beam deflectors which may be selected as pairs to be oriented responsive to drive signals for coupling a beam of light between a pair of optical fibers fixed in the fiber optic switching module. The fiber optic switching module also produces orientation signals from each light beam deflector which indicate its orientation.

In addition to the fiber optic switch module, the fiber optic switch also includes at least one portcard that supplies the drive signals to the fiber optic switching module for orienting at least one light beam deflector included therein. Furthermore, the portcard also receives the orientation signals produced by that light beam deflector together with coordinates that specify an orientation for the light beam deflector. The portcard compares the received coordinates with the orientation signals received from the light beam deflector and adjusts the drive signals supplied to the fiber optic switching module to reduce any difference between the received coordinates and the orientation signals.

In a preferred embodiment, the fiber optic switching module of the fiber optic switch includes a first and a second group of optical fiber receptacles which are separated from each other at opposite ends of a free space optical path. Each of these groups of optical fiber receptacles are adapted for receiving and fixing ends of optical fibers. The fiber optic switching module includes lenses juxtaposed with ends of optical fibers fixed respectively at the first and second groups and disposed along the optical path between the groups. Each of these lenses are respectively disposed with respect to an end of an associated optical fiber of the first or second group so that a beams of light as may be emitted from the end of the optical fiber pass through the immediately adjacent lens to propagate as a

5 quasi-collimated beams through the optical path from the lens toward the second or first group of optical fiber receptacles.

10 The preferred embodiment of the fiber optic switch also includes a first and a second sets of reflective light beam
5 deflectors that are both disposed along the optical path between the groups of optical fiber receptacles. Each of the sets of light beam deflectors are associated with one of the groups of
15 optical fiber receptacles and have a number of light beam deflectors that equals the optical fibers in the group with which it is associated. Each of the light beam deflectors in the first or the second set is:

- 20 1. associated with one of the optical fibers in the associated group of optical fiber receptacles;
- 15 2. along the optical path so the quasi-collimated beam of light as may be emitted from the lens associated with the optical fiber impinges upon the light beam deflector to be reflected therefrom through the optical path; and
- 25 3. energizable by drive signals supplied to the fiber optic switching module to be oriented for reflecting the quasi-collimated beam of light as may be emitted from the associated optical fiber to also reflect off a selected one of the light beam deflectors in the second or the first set.

30 In this way a pair of light beam deflectors, one light beam deflector of the pair belonging to the first set and one belonging to the second set, may be selected and oriented by the drive signals supplied to them to couple a quasi-collimated beam of light propagating through the optical path from the end of one
40 optical fiber fixed in an optical fiber receptacle either of the first or of the second group to reflect sequentially off the pair of energized light beam deflectors into a selected one of the optical fiber receptacles so as to enter an optical fiber as may be fixed at the second or at the first group of optical fiber
45 receptacles.

50 In a preferred embodiment the portcard of the fiber optic switch includes a driver circuit for supplying the drive signals to the fiber optic switching module for orienting at least one

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light beam deflector included in the fiber optic switching module. The portcard also includes a dual axis servo that receives coordinates which specify an orientation for the light beam deflector, and also receives the orientation signals produced by that light beam deflector. The portcard compares the received coordinates with the orientation signals received from the light beam deflector and adjusts the drive signals supplied to the fiber optic switching module to reduce any difference between the received coordinates and the orientation signals.

These and other features, objects and advantages will be understood or apparent to those of ordinary skill in the art from the following detailed description of the preferred embodiment as illustrated in the various drawing figures.

15 Brief Description of Drawings

25

FIG. 1 is a block diagram illustrating a proposed, prior art three (3) stage fully non-blocking fiber optic switch;

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FIG. 2 is a plan view ray tracing diagram illustrating propagation of light beams through a trapezoidally-shaped free space, convergent beam N×N reflective switching module in accordance with the present invention;

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FIG. 3 is a plan or elevational schematic diagram illustrating a single beam of light as may propagate between sides A and B of the trapezoidally-shaped free space, convergent beam N×N reflective switching module depicted in FIG. 2 in accordance with the present invention;

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FIG. 4a is a perspective view ray tracing diagram illustrating propagation of light beams through an alternative embodiment, rectangularly-shaped free space, convergent beam N×N reflective switching module in accordance with the present invention;

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FIG. 4b is plan view ray tracing diagram illustrating propagation of convergent light beams through the rectangularly-shaped reflective switching module illustrated in FIG. 4a in accordance with the present invention;

FIG. 5 is a plan view ray tracing diagram illustrating propagation of light beams through an alternative embodiment, polygonally-shaped free space, convergent beam N×N reflective switching module in accordance with the present invention;

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FIG. 6 is a plan view ray tracing diagram illustrating propagation of light beams through a trapezoidally-shaped free space, convergent beam reflective switching module in accordance with the present invention that permits coupling a beam of light

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between any arbitrarily chosen pair of optical fibers;

FIG. 7 is a plan view ray tracing diagram illustrating propagation of light beams through an alternative trapezoidally-shaped free space, convergent beam $N \times N$ reflective switching module in accordance with the present invention which is more compact than the $N \times N$ reflective switching module depicted in FIG. 5;

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FIG. 8a is an elevational view illustrating a preferred, cylindrically shaped micro-lens adapted for use in the $N \times N$ reflective switching module;

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FIG. 8b is an elevational view illustrating a micro-lens adapted for use in the $N \times N$ reflective switching module that permits closer spacing between lenses and fibers;

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FIG. 9 is a partially cross-sectioned elevational view illustrating a block included both in the side A and in side B of the $N \times N$ reflective switching module depicted in FIG. 7 that receives tapered optical fiber collimator assemblies;

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FIG. 10 is a partially cross-sectioned plan view illustrating the block depicted in FIG. 9 that receives tapered optical fiber collimator assemblies;

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FIG. 11 is a partially cross-sectioned elevational view illustrating a micro-lens adapted for use in the $N \times N$ reflective switching module for concurrently switching light carried by a duplex pair of optical fibers;

FIG. 12 is an elevational view illustrating a preferred type of silicon wafer substrate used in fabricating torsional scanners;

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FIG. 13 is a plan view illustrating a 2D electrostatically energized torsional scanner particularly adapted for use in reflective switching modules such as those illustrated in FIGS. 2, 4a-4b, 5, 6 and 7;

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FIG. 14 is an enlarged plan view illustrating a torsional flexure hinge used in the torsional scanner taken along the line 14-14 in FIG. 13;

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FIG. 15 is a schematic cross-sectional elevational view illustrating a torsional scanner disposed above an insulating substrate having electrodes deposited thereon with a beam of light reflecting off a mirror surface located on the backside of a device layer;

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FIGs. 15a and 15b are alternative plan views of the electrodes and a portion of the insulating substrate taken along the line 15a/15b-15a/15b in FIG. 15.

FIG. 16a is an elevational view illustrating a strip of torsional scanners adapted for use in reflective switching modules such as those illustrated in FIGs. 2, 4a-4b, 5, 6 and 7;

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FIG. 16b is a cross-sectional plan view taken along the line 16b-16b in FIG. 16a illustrating overlapping immediately adjacent strips of torsional scanners to reduce the horizontal distance between immediately adjacent strips;

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FIG. 16c is an elevational view illustrating a preferred strip of torsional scanners adapted for use in reflective switching modules such as those illustrated in FIGs. 2, 4a-4b, 5, 6 and 7;

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FIG. 16d is a cross-sectional plan view illustrating the preferred strip of torsional scanners taken along the line 16d-16d in FIG. 16c;

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FIG. 16e is a cross-sectional plan view taken along the line 16d-16d in FIG. 16a illustrating juxtaposition of the strips of torsional scanners depicted in FIG. 16c;

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FIG. 17a is a plan view illustrating vertically offset strips of torsional scanners which permits a denser arrangement of optical fibers in reflective switching modules such as those illustrated in FIGs. 2, 4a-4b, 5, 6 and 7;

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FIG. 17b is a plan view illustrating an even denser packing of offset rows or columns of torsional scanners that may be employed if all the torsional scanners are fabricated as a single monolithic array rather than in strips;

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FIG. 18a is a plan view illustrating an alternative embodiment of the torsional scanner in which the outer torsional flexure hinges are oriented diagonally with respect to the scanner's outer frame;

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FIG. 18b is a plan view illustrating an array of torsional scanner of the type illustrated in FIG. 18a;

FIG. 19a is a plan view illustrating an alternative embodiment of the torsional scanner in which the inner torsional flexure hinges are oriented along a diagonal of the scanner's non-square mirror plate;

FIG. 19b is a plan view illustrating an alternative embodiment of the torsional scanner depicted in FIG. 19a in which both pairs of torsional flexure hinges are suitably oriented with respect to crystallographic directions of silicon to permit fabrication of torsion sensors therein that have optimum characteristics;

FIG. 20a is an elevational view illustrating a dense arrangement of the torsional scanner illustrated in FIG. 18a adapted for inclusion in reflective switching modules such as those illustrated in FIGs. 2, 4a-4b, 5, 6 and 7;

FIG. 20b is an elevational view illustrating a dense arrangement of the torsional scanner illustrated in FIG. 19a adapted for inclusion in reflective switching modules such as those illustrated in FIGs. 2, 4a-4b, 5, 6 and 7;

FIG. 21 is a schematic cross-sectional elevational view illustrating an alternative embodiment strip of torsional scanners fastened to a substrate which also carries a mirror strip thereby permitting an arrangement in which collimator lenses and ends of optical fibers are positioned close to mirror surfaces on the torsional scanners;

FIGs. 22a is a front elevational view of a strip of torsional scanners flip-chip bonded to a substrate;

FIGs. 22b is a cross-sectioned, side elevational view of the strip of torsional scanners flip-chip bonded to the substrate taken along the line 22b-22b in FIG. 22a;

FIGs. 22c is a top view of the strip of torsional scanners that is flip-chip bonded to the substrate taken along the line 22c-22c in FIG. 22a;

FIGs. 22d is a cross-sectioned, side elevational views of the strip of torsional scanners flip-chip bonded to a silicon substrate having vias formed therethrough;

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FIG. 23 is a ray tracing diagram illustrating scattering of light from portions of a torsional scanner that surrounds the mirror surface thereof;

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FIG. 24 is a system level block diagram illustrating reflective switching modules such as those illustrated in FIGs. 2, 4a-4b, 5, 6 and 7;

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FIG. 25 is a perspective drawing illustrating a modular fiber optic switch in accordance with the present invention;

FIG. 26 is a overall block diagram for modular fiber optic switch depicted in FIG. 25 including a portcard and the reflective switching module;

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FIG. 26a is a diagram illustrating one embodiment of photo-detectors that may be used in an optical alignment servo for precisely orienting a pair of mirrors included in the reflective switching module;

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FIG. 26b is a diagram illustrating a compound photo-detector that may be used in an optical alignment servo for precisely orienting a pair of mirrors included in the reflective switching module;

30

FIG. 27a is a block diagram illustrating a servo system which ensures precise alignment of mirrors included in a reflective switching module included in the modular fiber optic switch depicted in FIG. 25, such as one of the reflective switching modules illustrated in FIGs. 2, 4a-4b, 5, 6 and 7;

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FIG. 27b is a block diagram illustrating one channel, either x-axis or y-axis, of a dual axis servo included in the servo system depicted in FIG. 27a;

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FIG. 28a is a partially cross-sectioned elevational view illustrating an alternative embodiment double plate structure for receiving and fixing an array of optical fibers;

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FIG. 28b is an elevational view illustrating a profile for one type of hole that may be formed through one of the plates taken along the line 28b-28b in FIG. 28a;

FIG. 28c is an elevational view illustrating an array of XY micro-stages formed in one of the plates taken along the line 28c-28c in FIG. 28a;

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FIG. 29a is an elevational view illustrating an XY micro-stage of a type included array taken along the line 29a-298 in FIG. 28c;

FIGs. 29b and 29c are elevational views illustrating a portion of alternative embodiment XY micro-stages taken along the line 29b/29c-29b/29c in FIG. 29a;

FIG. 30a is a partially cross-sectioned view illustrating a lens micromachined from a silicon substrate that can be electrostatically activated to move along the lens' longitudinal axis;

FIG. 30b is an elevational view illustrating the silicon micromachined lens taken along the line 30b-30b in FIG. 30a;

FIG. 30c is a partially cross-sectioned view illustrating a lens micromachined from a silicon substrate, similar to the lens illustrated in FIG. 30a, that can be electro-magnetically activated to move along the lens' longitudinal axis; and

FIG. 31, is an elevational view that illustrates coupling beams of light from a routing wavelength demultiplexer directly into one of the reflective switching modules illustrated in FIGs.

2, 4a-4b, 5, 6 and 7.

Best Mode for Carrying Out the Invention

Free Space, Convergent Beam, Double Bounce, Reflective Switching Module

FIG. 2 depicts ray tracings for light beams propagating through a trapezoidally-shaped, convergent beam, double bounce N×N reflective switching module in accordance with the present invention that is referred to by the general reference character 100. The N×N reflective switching module 100 includes sides 102a and 102b which are spaced apart from each other at opposite ends of a C-shaped free space optical path. Although as described below other geometrical relationships for the sides 102a and 102b may occur for other configurations of the N×N reflective switching module 100, for the embodiment of the N×N reflective switching module 100 illustrated in FIG. 2 having the C-shaped free space optical path the sides 102a and 102b are preferably

5 coplanar. Both side 102a and side 102b are adapted to receive
and fix ends 104 of N optical fibers 106, for example one-
thousand one-hundred fifty-two (1152) optical fibers 106. The
10 N optical fibers 106 are arranged in a rectangular array with
5 thirty-six (36) columns, each of which contains thirty-two (32)
optical fibers 106. A lens 112 is disposed immediately adjacent
to the ends 104 of each of the optical fibers 106 along the
15 optical path between sides 102a and 102b. Each of the lenses 112
are disposed with respect to the end 104 of the optical fiber 106
10 with which it is associated to produce from light, which may be
emitted from the end 104 of the associated optical fiber 106, a
quasi-collimated beam that propagates along the optical path
20 between sides 102a and 102b.

FIG. 3 graphically illustrates a single beam of light 108
15 from a single optical fiber 106 as may propagate between sides
102a and 102b, or conversely. For wavelengths of light conven-
25 tionally used in single mode fiber optic telecommunications, the
lens 112 is a micro-lens which typically has a focal length of
2.0 to 12.0 mm. Such a lens 112 produces a quasi-collimated beam
20 preferably having a diameter of approximately 1.5 mm which
propagates along a five-hundred (500) to nine-hundred (900) mm
long path between the sides 102a and 102b. Since the N×N
reflective switching module 100 preferably uses the maximum relay
length of the lens 112, the end 104 of each optical fiber 106 is
35 positioned at the focal length of the lens 112 plus the Raleigh
range of the beam of light 108 emitted from the optical fiber
106. Consequently, if the end 104 of the optical fiber 106 is
40 displaced a few microns along the axis of the lens 112, that
produces a negligible effect on the direction along which the
30 maximum relay length quasi-collimated beam propagates between the
sides 102a and 102b. Typically the exit angle of the maximum
relay length quasi-collimated beam from the lens 112 will be a
45 fraction of one milliradian, i.e. 0.001 radian. As will be
described in greater detail below, any possible misalignment of
35 the maximum relay length quasi-collimated beam due to misalign-
ment between the end 104 of the optical fiber 106 and the lens
112 can be easily accommodated by providing sufficiently large
50 surfaces from which the beam reflects.

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5 After passing through the associated lens 112, a beam of
light 108 emitted from the end 104 of each optical fiber 106
reflects first off a mirror surface 116a or 116b, indicated by
10 dashed lines in FIG. 3, that is associated with a particular lens
5 112 and optical fiber 106 pair. The mirror surfaces 116,
described in greater detail below, are preferably provided by
two-dimensional ("2D") torsional scanners of a type similar to
15 those described in United States Patent No. 5,629,790 ("the '790
patent"), that is incorporated herein by reference. The $N \times N$
20 reflective switching module 100 includes two sets 118a and 118b
of mirror surfaces 116 respectively disposed between the lenses
112 along the optical path between the sides 102a and 102b. Each
set 118a or 118b includes a number of individual, independent
25 mirror surfaces 116, each of which is supported by a pair of
gimbals that permits each mirror surface 116 to rotate about two
non-parallel axes. The number of mirror surfaces 116 equals the
number, N , of optical fibers 106 and lenses 112 at the nearest
side 102a or 102b. After reflecting off the mirror surface 116a
or 116b, the beam of light 108, propagating between sets 118a and
30 118b in FIG. 2, then reflects off a selected one (1) of the
mirror surface 116b or 116a further along the C-shaped optical
path between the sides 102a and 102b, through one of the lenses
112 at the distant side 102b or 102a, and into the optical fiber
106 associated with that particular lens 112.

35 25 FIGS. 4a-4b depict ray tracings for light beams propagating
through an alternative embodiment, rectangularly-shaped,
convergent $N \times N$ reflective switching module 100. The rectangular-
ly-shaped configuration of the $N \times N$ reflective switching module
40 100 illustrated in FIGS. 4a-4b employs a horizontally-elongated
30 Z-shaped free space optical path. While in the illustration of
this FIG. the distances between the side 102a and the curved set
118a, the curved set 118a and the curved set 118b, the curved set
45 118b and the side 102b are substantially equal, those skilled in
the art will recognize that these distances need not be equal.
35 Moreover, those skilled in the art will recognize that the sets
118a and 118b may be curved to provide either one dimensional
50 ("1D") or 2D convergence. Thus, for the configuration of the $N \times N$
reflective switching module 100 depicted in FIGS. 4a-4b the

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5 curved set 118a may be advantageously moved nearer to the side
102a and the curved set 118b moved nearer to the side 102b. Such
a shortening of the distances between the sides 102a and 102b and
the curved sets 118a and 118b correspondingly lengthens the
5 distance between the curved set 118a and curved set 118b which
produces a parallelogram-shaped $N \times N$ reflective switching module
100. FIG. 5 depicts ray tracings for light beams propagating
15 through an alternative embodiment, polygonally-shaped $N \times N$
reflective switching module 100. The polygonally-shaped
10 configuration of the $N \times N$ reflective switching module 100
illustrated in FIG. 5 also produces a Z-shaped free space optical
20 path.

FIG. 6 depicts a trapezoidally-shaped reflective switching
module 100 that consist of only one half of the $N \times N$ reflective
15 switching module 100 depicted in FIG. 1, i.e. either the left
half thereof or the right half thereof. The reflective switching
25 module 100 depicted in FIG. 6 fundamentally differs from that
depicted in FIG. 1 only by including a mirror 120 disposed at the
middle of the optical path between sides 102a and 102b. While
20 for equivalent sides 102a the reflective switching module 100
depicted in FIG. 6 can couple light selectively between only one-
half as many optical fibers 106 as the $N \times N$ reflective switching
module 100 illustrated in FIG. 1, the reflective switching module
100 depicted in FIG. 6 can couple light between any arbitrarily
35 chosen pair of those optical fibers 106. FIG. 7 depicts another
trapezoidally shaped $N \times N$ reflective switching module 100 which
also employs a mirror 120 for folding the optical path of the $N \times N$
reflective switching module 100 depicted in FIG. 5. Folding the
40 optical path into a W-shape provides a more compact reflective
switching module 100 than the $N \times N$ reflective switching module 100
30 depicted in FIG. 1.

Considering the beam of light 108 depicted schematically in
45 FIG. 3, solely from the perspective of optical design, the
various different embodiments of the reflective switching module
100 described above and illustrated in FIGs. 2, 4a, 4b, 5, 6, and
35 7 differ principally in the location of the mirror surfaces 116a
and 116b along the beam of light 108, and in the folding of the
50 optical path. For example, in the embodiment of the $N \times N$

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reflective switching module 100 illustrated in FIGs. 4a-4b the mirror surfaces 116a and 116b are located approximately one-third ($\frac{1}{3}$) of the path length between the sides 102a and 102b from the nearest lenses 112. Conversely for other configurations of the reflective switching module 100 such as those illustrated in FIGs. 2, 5, 6, and 7 the mirror surfaces 116a and 116b are immediately adjacent to the respective sides 102a and 102b. However, those skilled in the art of optical design will readily understand that differences among the various configurations, particularly locations for the mirror surfaces 116a and 116b with respect to the lenses 112 and the ends 104 of the optical fibers 106, influence or affect other more detailed aspects of the optical design.

Those skilled in the art of optical design will also understand that conceptually there exist an unlimited number of other possible geometrical arrangements and optical path shapes in addition to those illustrated in FIGs. 2, 4a, 4b, 5, 6 and 7 for placing the ends 104 of the optical fibers 106 respectively at one or more the sides 102a and 102b, the associated lenses 112 and the mirror surfaces 116a and 116b. With regard to such alternative geometrical arrangements for the free space optical path of the reflective switching module 100, a preference for one arrangements in comparison with other possible arrangements usually involves issues related to suitability for a particular optical switching application, size, ease of fabrication, relaxing mechanical tolerances for assembly of the reflective switching module 100, reliability, cost, etc. Specifically, the trapezoidally-shaped, convergent beam N×N reflective switching module 100 with the W-shaped free space optical path illustrated in FIG. 7 is presently preferred because:

1. it fits within a standard twenty-three (23) inch wide telecommunications rack;
2. mechanical tolerances are acceptable;
3. long effective relay length for the beams of light 108; and
4. runs for electrical cables and optical cables are well separated.

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5 As described above, the beam of light 108 produced by the
lens 112 from light emitted from the end 104 of the associated
optical fiber 106 first impinges upon the associated mirror
10 surface 116 of one of the torsional scanners included in the sets
5 118a and 118b. As described in greater detail below, for the
configuration of the N×N reflective switching module 100 depicted
in FIG. 7, the mirror surfaces 116 are preferably provided by
15 thirty-six (36) linear strips of thirty-two (32) torsional
scanners. Preferably, all thirty-two (32) mirror surfaces 116
10 in each strip are substantially coplanar. As an example, within
each strip immediately adjacent mirror surfaces 116 may be spaced
20 3.2 mm apart, and the immediately adjacent columns of mirror
surfaces 116 are preferably spaced 3.2 mm apart with respect to
the beams of light 108 impinging thereon from the immediately
15 adjacent sides 102a and 102b.

25 Also for all the various configurations of the N×N reflective
switching module 100, the ends 104 of the optical fibers
106, the lenses 112, and the mirror surfaces 116 of un-energized
torsional scanners are preferably oriented so all of the beams
30 of light 108 produced by light emitted from optical fibers 106
having their ends 104 at the side 102a converge at a point 122b
that is located behind the set 118b of mirror surfaces 116.
Correspondingly, the beams of light 108 emitted from optical
35 fibers 106 having their ends 104 at the side 102b converge at a
point 122a that is located behind the set 118a of mirror surfaces
116. Horizontally the convergence point 122 is established by
considering mirror surfaces 116 at opposite sides of the sets
40 118a and 118b. The point 122 lies at the intersection of two
lines that respectively bisect angles having their vertices at
30 those two mirror surface 116 and sides which extend from the
respective mirror surfaces 116 through mirror surfaces 116 at
opposite ends of the other set 118b or 118a. The point 122 is
45 located vertically one-half the height of the sets 118a and 118b.
The geometrical arrangement of the ends 104 of the optical fibers
35 106, the lenses 112, and the mirror surfaces 116 which produces
the preceding convergence provides equal clockwise and counter-
clockwise rotation angles and minimal rotation angles for mirror
50 surfaces 116 for each of the sets 118a and 118b that exhibit the

5 greatest movement in reflecting a beam of light 108 from one
mirror surface 116 in the set 118a or 118b to any of the mirror
surfaces 116 in the other set 118b or 118a. If in the configura-
10 tion for the N×N reflective switching module 100 depicted in FIG.
5 7 a pair of mirror surfaces 116a and 116b are separated six-
hundred and fifty (650) mm along the beam of light 108, then the
maximum angular rotation of the mirror surfaces 116 is approxi-
15 mately 3.9° clockwise and counter-clockwise.

Although individual pairs of optical fibers 106 and lenses
10 112 could be inserted into grooves to assemble the sides 102a and
102b which yield the convergence of the beams of light 108
described in the preceding paragraph, for maximum density of
20 lenses 112 and optical fibers 106 a monolithic block is prefera-
bly used that has holes appropriately pre-drilled therein. Each
15 pre-drilled hole receives one of the lenses 112 and a conven-
tional optical fiber ferrule secured about the end 104 of one
25 optical fiber 106. The compound angles required to align the
optical fiber 106 and the lens 112 for 2D convergence of the
beams of light 108 are provided by suitably orienting the holes
20 drilled into the block.

FIG. 8a depicts a preferred, cylindrically shaped micro-lens
112 fabricated with its focal point at, or as close as possible
to, a face 138 of the lens 112. As those skilled in the art of
35 fiber optics will understand, the optical fiber 106 emits the
25 beam of light 108 at an angle with respect to a center line of
the optical fiber 106 because the end 104 is polished at an angle
to eliminate reflections back from the end 104. Because the end
104 is angled, the axis of the beam of light 108 emitted from the
40 end 104 diverges from the longitudinal axis of the optical fiber
30 106. To align the beam of light 108 with a longitudinal axis 144
of the lens 112, the face 138 of the lens 112 is angled to center
the beam of light 108 within the lens 112. With the focal point
45 of the lens 112 at the face 138 as described above, the end 104
of the optical fiber 106 is positioned one Raleigh range of the
35 beam of light 108, e.g. 50-60 microns, from the face 138. The
diameter of a cylindrical surface 136 of the lens 112 is made
50 sufficiently large to contain the diverging beam of light 108

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5 before it exits the lens 112 through a convex surface 142 as the quasi-collimated beam of light 108.

10 This configuration for the lens 112 and the end 104 of the optical fiber 106 centers the beam of light 108 about the
5 longitudinal axis 144 of the lens 112 and the optical fiber collimator assembly 134 at the convex surface 142 of the lens 112, with the quasi-collimated beam of light 108 oriented
15 essentially parallel to the longitudinal axis 144. Usual manufacturing tolerances for the lens 112 described above produce
10 acceptable deviations in exit angle and offset of the beam of light 108 from the longitudinal axis 144 of the lens 112. For
20 example, if the lens 112 is fabricated from BK7 optical glass and the end 104 of the optical fiber 106 angles at 8° , then the angle of the beam of light 108 within the lens 112 is 6.78° , and the
15 lateral offset from the longitudinal axis 144 is less than 50 microns both at the face 138 and also 140 mm from the face 138. Such a well centered beam of light 108 permits reducing the
25 diameter of the surface 136 thus allowing the lenses 112 to be placed closer to each other. This lens 112 is preferably made
20 from Gradium material marketed by LightPath Technologies, Inc.

30 FIG. 8b depicts an alternative embodiment "champagne cork" shaped micro-lens 112 which advantageously permits spacing lenses 112 and optical fibers 106 closer together at the sides 102a and 102b. The lens 112 includes a smaller diameter surface 132 which
35 a conically-shaped optical fiber collimator assembly 134 illustrated in FIG. 9 receives. The larger diameter surface 136 of the lens 112 protrudes out of the optical fiber collimator assembly 134. The champagne cork shaped embodiment of the micro-lens 112 may be fabricated by grinding down a portion of the lens
40 112 illustrated in FIG. 8a.

45 As illustrated in FIG. 9, in addition to receiving one of either the cylindrically shaped lens depicted in FIG. 8a or the champagne cork shaped micro-lens 112 depicted in FIG. 8b, each optical fiber collimator assembly 134 also provides a receptacle
35 that receives a conventional fiber optic ferrule 146 secured about the end 104 of the optical fiber 106. A convergence block 152, one of which is respectively disposed at both sides 102a and 102b of the reflective switching module 100, is pierced by a
50

5 plurality of conically shaped holes 154 as illustrated in FIG.
10 that equal in number to the number N of optical fibers 106.
Convergence of the beams of light 108 as described above is
10 effected by the alignment of the optical fiber collimator
5 assemblies 134 upon insertion into the holes 154. The optical
fiber collimator assemblies 134 and holes 154 are preferably
formed from the same material with identically shaped, mating,
15 conical surfaces that taper at an angle of a few degrees.
Configured in this way, when all optical fiber collimator
10 assemblies 134 carrying the optical fibers 106 are fully seated
into their mating holes 154, the optical fiber collimator
20 assemblies 134 becomes fixed in the convergence block 152 and
hermetically seal the interior of the reflective switching module
100 through which the quasi-collimated beams of light 108
15 propagate.

25 The convergence block 152 may be simply machined out a
single piece of metal such as stainless steel, or from a ceramic
material, etc. Alternatively, the convergence block 152 may be
made out of Kovar, 42 % nickel-iron alloys, titanium (Ti),
30 tungsten (W) or molybdenum (Mo) suitably plated for corrosion
resistance. These materials all have coefficients of expansion
which approximately match that of the lenses 112 and minimize
birefringent effects that may take place as lenses 112 are heated
or cooled in their operating environment.

35 25 In addition to the preceding preferred way of providing
convergence by suitably orienting the optical fibers 106 and the
lenses 112 at each of the sides 102a and 102b, either 1D or 2D
40 convergence may also be obtained in other ways. For example, the
configuration of the optical fibers 106 and the lenses 112 could
30 provide some of the convergence which the arrangement of the
mirror surfaces 116 upon which the beams of light 108 first
impinge could provide the remainder of the convergence. For
45 example the mirror surfaces 116 in each column could be arranged
along a cylindrical surface. Alternatively, the optical fibers
35 106 and the lenses 112 might be arranged to provide none of the
convergence, i.e. beams of light 108 propagate parallel from the
50 sides 102a and 102b to the first mirror surfaces 116, with the
mirror surfaces 116 being arranged to provide all of the

5 convergence as illustrated in FIGs. 4a-4b. For example the
mirror surfaces 116 in each column could be arranged along a
spherical surface. Moreover, the optical fibers 106, lenses 112,
10 and sets 118a and 118b of mirror surfaces 116 may be arranged to
5 provide either 1D or 2D convergence either behind the sets 118a
and 118b or at the sets 118a and 118b. With regard to the
various alternative ways of arranging convergence of the beams
15 of light 108, selecting one way in comparison with other possible
ways usually involves issues related to ease of fabrication,
relaxing mechanical tolerances for assembly of the reflective
20 switching module 100, reliability, cost, etc.

The preceding convergence criterion not only affects the
optical design of the reflective switching module 100, that
criteria also interacts with reliability considerations. If each
15 optical fiber 106 of a reflective switching module 100 capable
of switching among 1152 optical fibers 106 carries a beam of
25 light 108 having a total power of 100 mW, the cumulative power
of all beams of light 108 passing through the reflective
switching module 100 at any instant is in excess of 100 watts.
30 However, assuming that, on average, equal numbers of the beams
of light 108 propagate in opposite directions between the sides
102a and 102b, then at any instant, on average, each set 118a or
118b of mirror surfaces 116 reflects beams of light 108 carrying
35 slightly more than 50 watts of power. From a worst-case analysis
perspective, at any instant beams of light 108 carrying at least
50 watts of power impinge either on one or the other of the set
118a or 118b of mirror surfaces 116. If electrical power
40 supplied to the reflective switching module 100 for orienting the
mirror surfaces 116 were to fail, then within a short time, e.g.
30 milliseconds, at least 50 watts of power and perhaps more than
100 watts of power becomes directed at the convergence point.
45 This amount of power would soon destroy the one or the few of the
mirror surfaces 116 included in the set 118a or 118b upon which
all of the beams of light 108 concentrate. To prevent such an
35 catastrophe from occurring, the sets 118a and 118b both omit any
mirror surfaces 116 from their centers where the beams of light
50 108 will converge if electrical power to the reflective switching
module 100 should fail. To detect such a failure, the reflective

5 switching module 100 may include a photo-detector behind this hole in the mirror surfaces 116.

10 In most telecommunication installations, optical fibers are generally matched as a duplex pair in which one fiber carries
5 communications in one direction while the other fiber of the pair carries communications in the opposite direction. Connectors adapted for coupling light between two duplex pairs of optical
15 fibers which secure the two optical fibers of a pair in a single ferrule are presently available. Because both optical fibers of
10 a duplex pair are switched concurrently, and because the reflective switching module 100 can couple light in either direction between a pair of optical fibers 106 one of which is
20 respectively located at side 102a and the other of which is located at side 102b, suitably adapting the lenses 112 for use
15 with duplex pairs of optical fibers 106 permits using a single pair of mirror surfaces 116a and 116b for switching light carried
25 in opposite directions respectively in the two optical fibers 106 of the duplex pair.

FIG. 11 depicts a lens 112 adapted for use in the reflective
20 switching module 100 for concurrently switching light carried by a duplex pair of optical fibers 106a and 106b. As illustrated in FIG. 11, the duplex optical fiber ferrule 146 carries the duplex pair of optical fibers 106a and 106b. The ends 104a and
30 104b of the optical fibers 106a and 106b and the faces 138a and 138b of the lens 112 are all polished at an angle. The angles
35 of the faces 138a and 138b are formed to compensate for the off-axis position of the optical fibers 106a and 106b so beams of light 108a and 108b impinging upon faces 138a and 138b from the
40 optical fibers 106a and 106b are formed into quasi-collimated beams which exit the convex surface 142 parallel to but slightly offset from the longitudinal axis 144, and propagate in that way
30 through the reflective switching module 100. Both of the beams of light 108a and 108b impinge upon the same pair of mirror surfaces 116a and 116b which are made large enough to simulta-
45 neously reflect both beams of light 108a and 108b. When the two quasi-collimated beams of light 108a and 108b impinge upon another identically configured lens 112 and duplex pair of
50 optical fibers 106 at the opposite side 102a or 102b of the

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reflective switching module 100, the lens 112 located there couples the beams of light 108a and 108b into the respective optical fibers 106 of the duplex pair.

5 Torsional Mirror Configuration

As described above, the mirror surfaces 116a and 116b of the sets 118a and 118b are preferably provided by electrostatically energized 2D torsional scanners of a type described in the '790 patent. United States Patent Application Serial No. 08/885,883
filed May 12, 1997, and published Patent Cooperation Treaty ("PCT") Patent Application International Publication Number: WO 98/44571, both of which are also incorporated by reference, provide additional more detailed information regarding the preferred 2D torsional scanner. Hinges which permit the mirror surfaces 116 to rotate about two (2) non-parallel axes preferably include torsion sensors of a type disclosed in United States Patent No. 5,648,618 ("the '618 patent") that is also incorporated herein by reference. The torsion sensors included in the hinges measure rotation of a second frame or a plate, that has been coated to provide the mirror surface 116, respectively with respect to the first frame or with respect to the second frame.

As described in the patents and patent applications identified above, torsional scanners are preferably fabricated by micro-machining single crystal silicon using Simox, silicon-on-insulator or bonded silicon wafer substrates. Such wafer substrates are particularly preferred starting material for torsional scanner fabrication because they permit easily fabricating a very flat, stress-free membrane, possibly only a few microns thick, which supports the mirror surfaces 116. As illustrated in FIG. 12, a silicon-on-insulator ("SOI") wafer 162 includes an electrically insulating silicon dioxide layer 164 that separates single crystal silicon layers 166 and 168. Torsion bars and plates that carry the mirror surfaces 116 of torsional scanners are formed in the thinner device silicon layer 166 while other portions of torsional scanners are formed by backside etching in the thicker handle silicon layer 168. As is well known to those skilled in the art of micro-machining, the device silicon layer 166 has a frontside 169 furthest from the

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5 handle silicon layer 168 and a backside 170 at the silicon
dioxide layer 164. The intermediate silicon dioxide layer 164
10 provides a perfect etch stop for etching the wafer 162 from its
backside, and yields torsion bars and plates having uniform
5 thickness.

FIG. 13 depicts a single electrostatically energized 2D
torsional scanner 172 adapted for providing the mirror
15 surfaces 116 for the reflective switching module 100. The
torsional scanner 172 includes an outer reference frame 174 to
10 which are coupled a diametrically opposed pair of outer torsional
flexure hinges 176. The torsional flexure hinges 176 support an
inner moving frame 178 for rotation about an axis established by
20 the torsional flexure hinges 176. A diametrically opposed pair
of inner torsional flexure hinges 182 couple a central plate 184
15 to the inner moving frame 178 for rotation about an axis
established by the torsional flexure hinges 182. The axes of
25 rotation established respectively by the torsional flexure hinges
176 and by the torsional flexure hinges 182 are non-parallel,
preferably perpendicular.

20 It is important to note that the plate 184 of the torsional
scanner 172 is rectangularly shaped with the longer side being
approximately 1.4 times wider than the height of the plate 184.
The plate 184 included in the reflective switching module 100 has
30 a rectangular shape because the beam of light 108 impinges
obliquely at an angle of 45° on the mirror surface 116 carried
35 by the plate 184. Consequently, for reflection of the beam of
light 108 from the mirror surface 116 the rectangularly shaped
plate 184 becomes effectively square. The plate 184 is prefera-
40 bly 2.5 mm x 1.9 mm, and is typically between 5 and 15 microns
thick as are the inner moving frame 178, the torsional flexure
30 hinges 176 and 182. The torsional flexure hinges 176 and 182 are
between 200 and 400 microns long, and between 10 and 40 microns
45 wide. The resonance frequencies on both axes are on the order
of 400 to 800 Hz which permits switching a beam of light 108
35 between two optical fibers 106 in approximately 1 to 5 millise-
conds. Both the frontside 169 and the backside 170 of the plate
50 184 are coated in perfect stress balance with identical metallic
adhesion layers, preferably 10.0 to 100.0 Å of titanium (Ti) or

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5 zirconium (Zr) which underlie a 500 to 800 Å thick metallic reflective layer of gold (Au).

10 The torsional flexure hinges 176 and 182, which are illustrated in greater detail in FIG. 14, provide various advantages in comparison with a conventional unfolded torsion bar. A United States patent application and a Patent Cooperation Treaty ("PCT") international patent application, which are both
15 entitled "Micromachined Members Coupled for Relative Rotation by Torsional Flexure Hinges," which were both filed September 2, 1999, by Timothy G. Slater and Armand P. Neukermans and which are both incorporated herein by reference, describe the various advantages provided by the torsional flexure hinges 176 and 182. Most significant for the reflective switching module 100, the torsional flexure hinges 176 and 182 are more compact than a
20 conventional unfolded torsion bar having an equivalent torsional spring constant. Consequently, use of the torsional flexure hinges 176 and 182 instead of a conventional unfolded torsion bar permits making much smaller torsional scanners 172 that can be packed more closely together which correspondingly increases the
25 number of optical fibers 106 that may be accommodated at the sides 102a and 102b of the reflective switching module 100.

Each torsional scanner 172 included in the reflective switching module 100 includes a pair of torsion sensors 192a and 192b, of a type disclosed in the '618 patent. The torsion
35 sensors 192a and 192b measure orientation of the supported member, i.e. the plate 184 or the inner moving frame 178, with respect to the supporting member, i.e. the inner moving frame 178 or the outer reference frame 174, at a theoretical resolution of
40 approximately 1.0 micro-radians. In accordance with the description in the '618 patent, when the torsional scanner 172 is operating in the reflective switching module 100 an electrical current flows in series through the two torsion sensors 192a and 192b between a pair of sensor-current pads 194a and 194b. Accordingly, the torsional scanner 172 includes a meandering
45 metal conductor 196 that is bonded to the frontside 169 of the device silicon layer 166. Starting at the sensor-current pad 194a, the meandering metal conductor 196 crosses the immediately adjacent torsional flexure hinge 176 from the outer reference
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5 frame 174 onto the inner moving frame 178 to reach the X-axis
torsion sensor 192b that is located in the lower torsional
flexure hinge 182. From the X-axis torsion sensor 192b the
10 meandering metal conductor 196 continues onto a reflective,
5 stress balanced metal coating, that is applied to both sides of
the plate 184 to provide the mirror surface 116, and across the
plate 184 and the upper torsional flexure hinge 182 back onto the
15 inner moving frame 178. The meandering metal conductor 196 then
leads to the Y-axis torsion sensor 192a that is located in the
10 left hand torsional flexure hinge 176. From the Y-axis torsion
sensor 192a, the meandering metal conductor 196 then curves
around the outer reference frame 174 to the sensor-current pad
20 194b. Metal conductors, that are disposed on opposite sides of
the meandering metal conductor 196 across the right hand
15 torsional flexure hinge 176 and on the inner moving frame 178,
connect a pair of inner-hinge sensor-pads 198a and 198b to the
25 X-axis torsion sensor 192b. Similarly, metal conductors, one of
which is disposed along side the meandering metal conductor 196
on the outer reference frame 174 and the other with curves around
20 the opposite side of the torsional scanner 172 on the outer
reference frame 174, connect a pair of inner-hinge sensor-pads
202a and 202b to the Y-axis torsion sensor 192a. A pair of
grooves 204, cut only through the device silicon layer 166 on
30 opposite sides of the inner-hinge sensor-pads 198a and 198b,
increase electrical isolation between the sensor-current pad 194a
35 and the inner-hinge sensor-pads 198a and 198b and the
sensor-current pad 194b and the inner-hinge sensor-pads 202a and
202b.

40 Preferably, the backside 170 of the plate 184 provides the
30 mirror surface 116 because, as illustrated in FIG. 15, the
frontside 169 faces an insulating substrate 212 which carries
both electrodes 214 used in energizing rotation of the plate 184
45 and contacts for the sensor-current pads 194a and 194b, the
inner-hinge sensor-pads 198a and 198b and the inner-hinge
35 sensor-pads 202a and 202b not illustrated in FIG. 15. The plates
184 of each torsional scanner 172 are separated a distance, e.g.
50 from 40 to 150 microns, from the substrate 212 by spacers which
are also not depicted in FIG 15. The separation between the

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5 plate 184 and the substrate 212 depends upon how far edges of the plate 184 move during rotation.

10 Note that for the reflective switching module 100 very thin plates 184, only a few microns thick, are desirable and can be
5 fabricated using the device silicon layer 166 of the wafer 162. In many instances the plate 184 and the torsional flexure hinges 176 and 182 can be made of the same thickness as the device
15 silicon layer 166. Alternatively, as illustrated in FIG. 15 the torsional flexure hinges 176 may be thinned by etching. For
10 example, the torsional flexure hinges 176 may be 6 microns thick while the plate 184 may be 10 microns thick. Analogously, the
20 plate 184 may be thinned to reduce its moment of inertia by etching a cavity 216 into the plate 184 leaving reinforcing ribs 218 on the thinned plate 184.

15 A telecommunication system component such as the reflective
25 switching module 100 must exhibit high reliability. A plate 184 of the torsional scanner 172 that accidentally collides with the electrode 214 should not stick to it, and should immediately
30 rotate to its specified orientation. Furthermore, such accidental collisions should not damage the torsional scanner 172, or
20 any circuitry connected to the torsional scanner 172. To preclude stiction, as illustrated in FIG. 13 the periphery of the plate 184 and of the inner moving frame 178 have rounded corners
35 that reduce the strength of the electrostatic field. Rounding
25 the periphery of the plate 184 also reduces its effective turning radius which results from compound rotation of the plate 184 about the axes respectively established by both torsional flexure
40 hinges 176 and 182.

40 In addition to rounding the periphery of the plate 184 and
30 the inner moving frame 178, as illustrated in FIG. 15a locations where the plate 184 may contact the electrodes 214 are overcoated with electrical insulating material 219 such as polyimide.
45 Overcoating only those portions of the electrodes 214 which may contact the plate 184 with the electrical insulating material 219
35 avoids charge stored on most of the electrodes 214. Analogously, during fabrication of the torsional scanner 172 some of the
50 silicon dioxide layer 164 may be left at the periphery of the plate 184 so the metallic reflective layer which provides the

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5 mirror surface 116 never contacts the electrode 214. Alternatively, as illustrated in FIG. 16b holes 220 are formed through the metal of the electrodes 214 in areas of possible contact.

10 During operation of the reflective switching module 100, the torsional scanner 172 is at a ground electrical potential while driving voltages are applied to the electrodes 214. To reduce electrical discharge currents if the plate 184 contacts the electrodes 214, large resistors (e.g. 1.0 MΩ) may be connected
15 in series with the driving circuit for the electrodes 214. Ideally these resistors should be located as close as practicable to the electrodes 214 otherwise the conductor connecting between the electrodes 214 and the resistors might pickup stray electric fields that rotate the plate 184. Therefore, one alternative is to overcoat the electrodes 214 with a very high resistivity but
20 slightly conductive material in selected areas such as those illustrated in FIG. 16a to provide a bleed path from the electrodes 214 for DC charges. Furthermore, inputs of all amplifiers connected to torsional scanners 172, such as those
25 which receive orientation signals from the torsion sensors 192a and 192b, should include diode protection to prevent damage from an over-voltage condition due to arcing or accidental contact between the plate 184 and the electrodes 214.

Several configurations exist that may be exploited advantageously to increase the density of the mirror array, which is
35 usually the limiting factor on the density of optical fibers 106 at the sides 102a and 102b. For several reasons, particularly the large number of contacts that must be brought out for each torsional scanner 172, the torsional scanners 172 are preferably
40 arranged into strips 222 as illustrated in FIGs. 16a and 16b. Organizing the torsional scanners 172 into strips 222 increases their density above that which might be achieved if arranged as a 2 dimensional array of discrete torsional scanners 172. Each
45 strip 222 includes a metal support frame 224 to which the substrate 212 is fastened.

35 As explained in greater detail below, the strip 222 is flip-chip bonded to the substrate 212 so all electrical connections to the strip 222 are made between the strip 222 and the substrate 212. A flat polyimide backed multi-conductor ribbon cable 226
50

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5 connects to the substrate 212 to exchange electrical signals
between the pads 194, 198 and 202 and the electrodes 214. Since
each support frame 224 may be an open frame possibly including
10 reinforcing ribs, the ribbon cable 226 can be freely bent and
5 guided away from the substrate 212.

FIG. 16b illustrates how, without obscuring the mirror
surfaces 116, the substrates 212 and the strips 222 may be
15 overlapped with the ribbon cable 226 serpentine along the
staircased substrates 212. Arranging the strips 222 in this way
20 reduces the horizontal distance between the mirror surfaces 116
of immediately adjacent strips 222 in relationship to the beams
of light 108. Since the beams of light 108 impinge upon the
mirror surfaces 116 at approximately 45°, the apparent distance
between immediately adjacent strips 222 is further foreshortened
15 by a factor of approximately 1.4 which, as described above, is
why the plate 184 is preferably rectangularly shaped.

25 One disadvantage with the configuration of strips 222
illustrated in FIG. 16b is that the offset between immediately
adjacent strips 222 cannot be less than the thickness of the
torsional scanners 172 plus the substrate 212. Furthermore,
30 overlapping of immediately adjacent strips 222 and substrates 212
hinders removing a single defective strip 222 without disturbing
immediately adjacent strips 222.

FIGs. 16c and 16d illustrate a preferred embodiment for the
35 strips 222 and the support frames 224 in which electrical leads
228 that connect to the torsional scanners 172 are plated or
screened onto one face, around one edge, and onto the other face
of the substrate 212. With this configuration for the leads 228,
40 attachment of the ribbon cable 226 to the substrate 212 is
unhindered. Plating or screening the leads 228 onto the
30 substrate 212 and including some via holes through the substrate
212 permits the substrate 212 to be as narrow as the strip 222.
45 Narrowed to this extent, the combined strips 222, substrates 212
and support frames 224 may now be arranged as illustrated in FIG.
16e for both of the sets 118a and 118b. This permits the offset
35 between immediately adjacent strips 222 to be established as
required by the optics of the reflective switching module 100
50 rather than by packaging considerations. The optimum offset

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5 between immediately adjacent strips 222 is approximately 0% to
10% of the distance between plates 184 in immediately adjacent
strips 222. The configuration of the substrate 212 illustrated
10 in FIG. 16d facilitates access to the substrate 212 and removal
5 of the strip 222 without disturbing adjacent support frames 224.
Note that if necessary the leads 228 may be brought out around
both edges of the substrate 212. This capability may be
15 exploited advantageously to separate leads 228 carrying high
voltage driving signals that are applied between the plate 184
10 and the electrodes 214 from leads 228 which carry signals from
the torsion sensors 192a and 192b.

20 Without reducing the size of the plate 184, as illustrated
in FIG. 17a the density of the optical fibers 106 at the sides
102a and 102b may be increased by offsetting the torsional
15 scanners 172 of immediately adjacent strips 222 vertically by
one-half the vertical distance between torsional scanners 172
25 within the strip 222. Due to the convergence criteria set forth
above for arranging the beams of light 108 within the reflective
switching module 100, offsetting the torsional scanners 172 in
20 immediately adjacent strips 222 effects a reorganization of the
holes 154 which receive the optical fiber collimator assemblies
134 from a quasi rectangular array into a quasi hexagonally close
packed array. While offsetting the torsional scanners 172 in
30 immediately adjacent strips 222 does not increase the density of
the torsional scanners 172, such an arrangement of the torsional
35 scanners 172 does increase the density of the optical fibers 106
at the sides 102a and 102b to the extent that the diameter,
either of lenses 112 or of optical fiber collimator assemblies
40 134, limits the spacing between immediately adjacent optical
30 fibers 106.

45 The density of torsional scanners 172 may be even further
increased by fabricating the torsional scanners 172 as completely
monolithic two dimensional arrays rather than as strips 222. As
illustrated in FIG. 17b, offsetting the torsional scanners 172
35 in immediately adjacent columns permits interdigitation of the
torsional flexure hinges 176 of torsional scanners 172 into an
empty space that occurs between torsional scanners 172 in
50 immediately adjacent columns or rows of the array. This

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interdigitating of the torsional flexure hinges 176 provides a shorter distance between centers of plates 184 of torsional scanners 172 in adjacent columns or rows, and more closely approximates a hexagonal close packing of the torsional scanners 172 and, correspondingly, of the optical fibers 106 at the sides 102a and 102b.

An alternative embodiment for strips 222 orients the torsional flexure hinges 176 and 182 at 45° with respect to the vertical and horizontal axes of the support frame 224. FIGS. 18a and 18b illustrate a diagonal configuration for the torsional flexure hinges 176 and 182 which more efficiently uses area on the strips 222 than a configuration in which the torsional flexure hinges 176 and 182 are oriented parallel and perpendicular to strips 222. Using a diagonal orientation for the torsional flexure hinges 176 and 182 oriented at 45° with respect to the outer reference frame 174, they can be longer without increasing the area occupied by the torsional scanner 172. The plate 184 is elongated in one direction to accommodate the 45° impingement angle of the beam of light 108. Due to the elliptical shape of the beam of light 108 as it impinges upon the plate 184, corners of the beam of light 108 may be eliminated resulting in an octagonally shaped plate 184, which conveniently provides room for the outer reference frame 174. Sides of the outer reference frame 174 are oriented in the <110> crystallographic direction of silicon for ease of fabrication. This configuration for the torsional scanner 172 orients the torsion sensors 192a and 192b along the <100> crystallographic direction of silicon. Thus, a wafer 162 having a p-type device silicon layer 166 or p-type implantation must be used in fabricating the torsion sensors 192a and 192b. The <110> and <100> crystallographic directions of silicon may be interchanged with suitable process changes.

Using the arrangement of the torsional scanner 172 illustrated in FIG. 18b, 1.5 × 2 mm plates 184 may be spaced only 2.5 mm apart effectively increasing the density of mirror surfaces 116 by a factor of 1.4. When viewed at the approximate 45° incident angle of the beams of light 108, the strips 222 slope at 54°. In this configuration the strips 222 are oriented at

5 45° to the support frames 224. This orientation of the strips
222 is necessary if the mirror surfaces 116 are to fully
10 intercept the beams of light 108. The support frames 224 could
be oriented at 45° which permits all the strips 222 to be the
5 same length, thereby using area on wafers 162 more efficiently.

FIG. 19a illustrates yet another alternative embodiment of
the torsional scanner 172 which further reduces its size thereby
15 further shortening distances between immediately adjacent mirror
surfaces 116 in the reflective switching module 100. From the
10 preceding description it is apparent that positioning the
torsional flexure hinges 176 and 182 at corners rather than sides
20 of the plate 184 advantageously reduces the size of the torsional
scanner 172. In FIG. 19a an elliptically-shaped curve 232
represents an outline of the beam of light 108 impinging on the
15 mirror surface 116 of the plate 184. Because the beam of light
25 108 does not impinge on the corners of the plate 184, the inner
torsional flexure hinges 182 may be rotated with respect to the
plate 184 to occupy unused corner space. As in the configuration
of the torsional scanner 172 illustrated in FIG. 18a, the outer
20 torsional flexure hinges 176 continues to occupy corners of the
30 outer reference frame 174.

Not only does placement of the torsional flexure hinges 182
at the corners of the plate 184 as illustrated in FIG. 19a reduce
the size of the torsional scanner 172, it also reduces compound-
35 ing of the angles when the plate 184 rotates simultaneously about
25 both axes. Compounding increases the distance through which
corners of the plate 184 move when the plate 184 simultaneously
rotates about axes established by both torsional flexure hinges
40 176 and 182. Compounding increases the separation required
30 between the plate 184 and the substrate 212 which correspondingly
increases the voltage that must be applied between the plate 184
and the electrodes 214 for equivalent performance in rotating the
45 plate 184. However, if the plate 184 has an aspect ratio that
is not square as will usually occur for plates 184 included in
35 the reflective switching module 100, then the torsion sensors
192a and 192b in torsional flexure hinges 176 and 182 depicted
50 in FIG. 19a are no longer oriented along orthogonal crystallo-
graphic directions, i.e. either <100> or <110> directions, of

5 silicon. This is undesirable, since the torsion sensors 192a and 192b in the torsional flexure hinges 176 and 182 then respond both to bending and torsion of the torsional flexure hinges 176 and 182.

10 5 Because the plate 184 depicted in FIG. 19a has an aspect ratio of approximately 1.4:1, axes of rotation 236a and 236b established by the torsional flexure hinges 176 and 182 intersect at approximately 70.5°. However, reorienting the axes of rotation 236a and 236b slightly until they intersect at 90°, as 15 illustrated in FIG. 19b, permits the torsional flexure hinges 176 and 182 to be oriented along a single crystallographic direction of silicon, e.g. the <100> crystallographic orientation if the outer reference frame 174 is aligned along the <110> crystallographic direction of silicon. Configured as illustrated in FIG. 20 19b, the torsional scanner 172 provides a significant amount of space for the inner torsional flexure hinges 182 in the corners of the plate 184 which reduces the size of the torsional scanner 172. Furthermore, the configuration of the torsional scanner 172 illustrated in FIG. 19b preserves the crystallographic orientation of the torsion sensors 192a and 192b while the compounding effect, though not completely eliminated, is significantly reduced. However, in the configuration of the torsional scanner 172 depicted in FIG. 19, the orthogonal axes of rotation established by the torsional flexure hinges 176 and 182 are 25 oriented obliquely to the length and width of the plate 184. Nevertheless, because only small angular rotations of the plate 184 occur during operation of the reflective switching module 100 the area of the plate 184 upon which the beam of light 108 impinges changes insignificantly when the plate 184 rotates.

30 30 Incorporating the torsional scanners 172 illustrated in FIGs. 18a or 19a into one of the set 118a or 118b of mirror surfaces 116 to maximize their respective advantages requires rearranging the shape of the set 118a or 118b. A preferred arrangement for strips 222' of torsional scanners 172 depicted 35 in FIG. 18a is illustrated in FIG. 20a. As described above and depicted FIG. 20a, the strips 222' are mounted at a 45° angle with respect to a horizontal base 242 of the reflective switching module 100. In the illustration of FIG. 20a, the support frames

5 224' carrying the strips 222' are also mounted at a 45° angle
with respect to the base 242. The two axes established by the
torsional flexure hinges 176 and 182 about which the plates 184
10 rotate are indicated by x and y axes 244 depicted in FIG. 20a.
5 The maximum rotation angles for plates 184 about axes established
by the torsional flexure hinges 176 and 182 allowed for identical
torsional scanners 172 at the other set 118b or 118a of mirror
15 surfaces 116 establishes a serrated rectangularly-shaped field
246 of addressable torsional scanners 172 in the addressed set
10 118a or 118b.

This optimum rectangularly-shaped field 246 is truncated at
20 the corners and has sides that are approximately diagonal to the
strips 222'. For the arrangement illustrated in FIG. 20a, the
longest strip 222' must include at least 1.4 times more torsional
15 scanners 172 than that required for a rectangular array of the
torsional scanners 172 assembled from the strip 222 illustrated
25 in FIG. 16a. However, torsional scanners 172 may be omitted from
locations in the set 118a or 118b that cannot be addressed from
the other set 118b or 118a. Thus, only a few of the strips 222'
20 illustrated in FIG. 20a need be full length. Those strips 222'
that include only a few torsional scanners 172 might even be
eliminated entirely. For example by using 40 strips 222'
30 containing a maximum 44 torsional scanners 172, it is possible
to arrange as many as 1152 torsional scanners 172 in the set 118a
35 or 118b, with very small scan angles, and relatively small mirror
sizes. A different arrangement provides for 1132 torsional
scanners 172, which measure only 1.59 by 2.2 mm, and requires
40 deflection angles of 3.69° and 3.3°. The strips 222' of the
torsional scanners 172 are oriented at an average of 55° to the
30 optical fiber collimator assemblies 134. The arrangement
illustrated in FIG. 20a, though slightly more complex substan-
tially increases the density of the torsional scanners 172 and,
45 correspondingly, the optical fiber collimator assemblies 134, and
allows more scanners to be addressed for particular rotation
35 angles specified for the plates 184.

FIG. 20b illustrates an analogous re-arrangement at the sets
50 118a and 118b of torsional scanners 172 of the type depicted in
FIG. 19b. For this arrangement of the torsional scanners 172

5 depicted in FIG. 19b the strips 222" and the support frames 224"
are oriented vertically similar to the illustration of FIG. 16a.
However, the x and y axes 244 about which the plate 184 rotate
10 are oriented at 45° with respect to the strips 222" and their
5 support frames 224". The oblique orientation of the x and y axes
244 with respect to the strips 222" and the support frames 224"
again means that the maximum rotation angles for plates 184 of
15 corresponding torsional scanners 172 at the other set 118b or
118a of mirror surfaces 116 establishes a serrated octagon or
10 truncated rectangularly-shaped field 256 of addressable torsional
scanners 172 at the addressed set 118a or 118b. If the
20 rectangularly-shaped field 256 established for these torsional
scanners 172 is $p \times q$, then the optimum field coverage for strips
is a square or rectangular field with an area of .7 to 1.2 pq ,
15 symmetrically arranged along the diagonal x and y axes 244. This
results in an aspect ratio for the rectangularly-shaped field 256
25 that is slightly elongated in the direction of the strips 222",
e.g. 1.0:1.3. If the set 118a or 118b have horizontally oriented
strips 222" and support frames 224", then the elongation of the
20 rectangularly-shaped field 256 becomes horizontal rather than
vertical. For manufacturing convenience, all strips 222" are
made the same length. Analogous to the arrangement of torsional
scanners 172 depicted in FIG. 20a, there again exist areas of the
30 rectangularly-shaped field 256 which can omit torsional scanners
172. Again it is advantageous to omit shorter strips 222" along
35 the sides of the rectangularly-shaped field 256 which have few
torsional scanners 172, and to slightly elongate others strips
222". In the example illustrated in FIG. 20b, for a 1.8 by 2.4
40 mm plate 184 and rotation angles for the plates 184 about the x
and y axes 244 of 5.6° and 3.7° the arrangement significantly
30 increases the number of torsional scanners 172 to approximately
1,500.

45 In the configurations of the reflective switching module 100
described thus far, the optical fiber collimator assemblies 134
35 are fastened in the convergence block 152 which is located some
distance from at least portions of the sets 118a and 118b of
50 mirror surfaces 116. This configuration for the reflective
switching module 100 requires very good alignment of the

5 collimators to the mirror surfaces 116. FIG. 21 illustrates an
arrangement of whereby the collimating lens 112, optical fibers
106 and strips 222 of torsional scanners 172 are brought closer
10 together thereby relaxing tolerances for their alignment. In
5 that illustration, the substrate 212 is made wider than the strip
222 and a mirror strip 262 attached to the surface of the
substrate 212 opposite to the strip 222 to establish a beam-
15 folding and deflecting assembly 264. The beam-folding and
deflecting assemblies 264 are then arranged into a repeating,
10 regular structure in which the quasi-collimated beam of light 108
reflecting off the mirror strip 262 of one beam-folding and
deflecting assembly 264 impinges upon the mirror surface 116
20 provided by the immediately adjacent torsional scanner 172.
Since in the arrangement illustrated in FIG. 21 all the lenses
15 112 are located an identical short distance from their associated
mirror surface 116, alignment of the beams of light 108 to their
25 respective mirror surfaces 116 is less critical. Convergence of
the beams of light 108 may be provided in one dimension by
arranging immediately adjacent beam-folding and deflecting
30 assemblies 264 at slightly differing angles. Convergence in a
second dimension may be obtained by appropriately positioning the
optical fibers 106 and lenses 112 with respect to their respec-
tive associated mirror surfaces 116. Because in the arrangement
35 illustrated in FIG. 21 the substrates 212 are near their
25 associated mirror surface 116, almost the entire five-hundred
(500) to nine-hundred (900) mm long path between the sides 102a
and 102b is between pairs of mirror surfaces 116 in the sets 118a
and 118b thereby reducing the angles through which the plates 184
40 must rotate.

30 As illustrated in FIG. 13, all electrical connections to the
torsional scanners 172 occur at the frontside 169 of the device
silicon layer 166, and as illustrated in FIG. 15 the beam of
45 light 108 reflects off a metallic layer coated onto the backside
170 of the device silicon layer 166. To form electrical
35 connections between the substrate 212 and the torsional scanners
172 in the strip 222, the strip 222 is preferably flip-chip
50 bonded to the substrate 212. The substrate 212 may accommodate
more than one strip 222 by using a substrate 212 that is larger

5 than the strip 222. The substrate 212 may be fabricated in various different ways.

10 The substrate 212 may be fabricated from a 100 wafer of silicon. If the substrate 212 is fabricated from a silicon
5 wafer, then cavities 272 may be anisotropically etched into the substrate 212 to provide space for rotation of the plates 184, and to establish a precisely controlled spacing between the plate
15 184 and electrodes 214 located in the cavities 272. Electrical insulation between leads 228 and between electrodes 214 may be
10 obtained by forming an electrically insulating oxide on the surface of the silicon substrate 212. The electrodes 214 may
20 either be integrated into the silicon substrate 212 or deposited onto the silicon surfaces within each of the cavities 272.

25 If the substrate 212 is fabricated from a silicon wafer, then electronic circuits may also be advantageously integrated
25 thereinto. The circuits included in a silicon substrate 212 may include current sources for providing an electrical current to the torsion sensors 192a and 192b of the torsional scanners 172,
30 differential amplifiers for receiving signals from the torsion sensors 192a and 192b which indicate the orientation of the inner
30 moving frame 178 and the plate 184, and amplifiers for supplying high voltage signals to the electrodes 214 that energize rotation
35 of the plate 184. Incorporating these various different type of electronic circuits into the substrate 212 significantly reduces
25 the number of leads that must be included in the ribbon cable 226. The number of leads in the ribbon cable 226 may be even
40 further reduced by including one or more multiplexer circuits in the silicon substrate 212.

40 Photo-detectors which respond to a wavelength of light present in the beam of light 108 and which are disposed on the
30 surface of the substrate 212 adjacent to the strip 222 outside shadows cast by the mirror surfaces 116 may be advantageously
45 included on the substrate 212 to detect if a portion of the beam of light 108 misses the mirror surfaces 116. For wavelengths of
35 light used for optical fiber telecommunications, such photo-detectors sense if a portion of the beam of light 108 misses the
50 mirror surfaces 116 even if they are covered by portions of the strip 222 other than the mirror surfaces 116 because silicon is

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transparent to light at wavelengths used for optical fiber telecommunications.

The strip 222 is joined to the substrate 212 by solder-bumps 276 or other bonds formed by solder reflow. The solder-bumps 276 rigidly interconnect pads on the substrate 212 with the pads 194, 198 and 202 of the torsional scanners 172 of the strip 222. The flip-chip bonding of the similar material strip 222 and substrate 212 perfectly matches temperature coefficients between them, and therefore introduces no stresses which keeps the strip 222 flat.

If the substrate 212 is fabricated from silicon or from polysilicon, then as depicted in FIG. 22d a large number of very small electrically conductive vias 282 may be formed, using a process similar to that described by Calmes, et al. in Transducers 99 at page 1500, through the silicon wafer during fabrication of the substrate 212. Holes for the vias 282 are first formed through the wafer using the standard Bosch deep reactive ion etch ("RIE") process. The holes may be 50 micron wide and 500 micron deep. The wafer is then oxidized thus establishing an electrically insulating oxide layer 284 which isolates the hole from the surrounding wafer. Then a highly doped polysilicon layer 286 is grown over the oxide layer 284 by providing a conductive path along the surface of wafer and in the holes. Obtaining a sufficiently conductive polysilicon layer may also require gas phase doping of the polysilicon layer 286 with phosphorus. The conductive polysilicon layer 286 formed in this way electrically connects both sides of wafer. If desired, rings 288 may then be etched through the polysilicon layer 286 around each via 282 thereby electrically isolating the vias 282 from each other. To increase electrical conductivity of substrate 212 and to facilitate forming an electrical contact to the vias 282, one or more additional metal layers may be coated either on one or both sides of the substrate 212 and appropriately patterned.

Mounting of the strip 222 to the substrate 212 that includes the vias 282 is depicted in FIG. 22d. Electrical connections between the strip 222 and vias 282 of the substrate 212 are again formed by solder-bumps 276. An elastomer layer 292 fastens a polyimide and copper sheet 294 which forms the ribbon cable 226 to the side of the substrate 212 furthest from the strip 222 of

5 torsional scanners 172. Ballgrid or TAB bumps 298 make contact
to the conductive vias 282 to establish electrical connections
with the polyimide and copper sheet 294. In this way a very
10 large number of contacts to be brought through the substrate 212
5 with relatively low electrical resistance vias 282.

If the substrate 212 is fabricated from polysilicon or from
Pyrex glass, then the cavities 272 may be etched thereinto.
15 However, if the substrate 212 is made from Pyrex then the
electrodes 214 must be deposited onto the surfaces of the
10 cavities 272. The substrate 212 may also be fabricated from a
suitable ceramic such as aluminum oxide or preferably aluminum
nitride which has a coefficient of thermal expansion that more
20 closely matches that of the silicon forming the strip 222. If
the strip 222 is fabricated from a ceramic material, then a
15 spacer must be screened onto the substrate 212 to provide space
for rotation of the plates 184, and to establish a precisely
25 controlled spacing between the plate 184 and the electrodes 214.
However, forming spacers on the surface of a ceramic substrate
212 usually requires repetitive coatings to establish a suffi-
20 cient gap between the electrodes 214 and the plate 184.

30 Note that steep sides 302 formed by 111 planes exposed by
anisotropic etching of the handle silicon layer 168 of the wafer
162, illustrated in FIG. 15, prove very advantageous for flip-
chip bonding. Not only do the sides 302 substantially protect
35 the mirror surface 116 on the backside 170 of the plate 184 from
damage during manufacturing while concurrently mechanically
reinforcing the strip 222, but their steep angle scarcely
obscures the beam of light 108 impinging upon the mirror surface
40 116 at an angle of approximately 45°. Furthermore, the mirror
30 surface 116 may be protected from contamination by stretching an
extremely thin pellicle 304, similar to those used for integrated
circuit ("IC") masks, across the backside of the handle silicon
45 layer 168.

Due to the presence of the handle silicon layer 168
35 surrounding the mirror surface 116, the flip-chip configuration
for mounting the torsional scanner 172 also permits advantageously
50 reducing light scattering as illustrated in FIG. 23. The
steep sides 302 and surrounding backside of the handle silicon

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5 layer 168 may be coated with an anti reflection layer 312 which
effectively absorbs stray light impinging thereon as the beam of
light 108 switches between mirror surfaces 116. The steep sides
10 302 also scatter stray light from the beam of light 108 at very
5 large angles which prevents the side 102a or 102b toward which
the beam of light 108 propagates from receiving stray light as
the beam of light 108 switches between mirror surfaces 116.

15 FIG. 24 schematically illustrates the reflective switching
module 100, such as those illustrated in FIGs. 2, 4a-4b, 5, 6 and
10 7 as described thus far, encased within an environmental housing
352 that completely encloses the optical path through which the
beams of light 108 propagate. As described above, the reflective
20 switching module 100 mechanically interconnects the sides 102a
and 102b and the sets 118a and 118b and keeps them rigidly
15 aligned. The environmentally sealed environmental housing 352,
which protects the reflective switching module 100, may provide
25 temperature regulation thereby maintaining a stable operating
environment for the reflective switching module 100. A con-
trolled, dry gas, such as nitrogen, may flow through the
30 environmental housing 352 to hinder moisture from condensing
within the reflective switching module 100. The environmental
housing 352 may also be slightly pressurized to exclude the
surrounding atmosphere from the reflective switching module 100.
35 The environmental housing 352 may include a nonsaturable
25 microdryer 353 as described in United States Patent No. 4,528,078
to control the humidity of atmosphere within the reflective
switching module 100. A wall 354 of the environmental housing
40 352 is pierced by electrical feed-throughs 356 for ribbon cables
226. The optical fiber collimator assemblies 134 secured about
30 the ends 104 of the optical fibers 106 plug directly into the
convergence blocks 152 which project through the environmental
housing 352. In this way, the environmental housing 352 almost
45 hermetically encloses the reflective switching module 100.
Within the environmental housing 352, to reduce the possibility
35 of optical misalignment, the ribbon cables 226 are routed
carefully to avoid applying stresses to the reflective switching
50 module 100, particularly the support frames 224 and the sub-
strates 212.

Fiber Optic Switch

FIG. 25 illustrates a modular fiber optic switch in accordance with the present invention referred to by the general reference character 400. The fiber optic switch 400 includes a standard twenty-three (23) inch wide telecommunications rack 402 at the base of which is located the environmental housing 352 containing the reflective switching module 100. The environmental housing 352 containing all the torsional scanners 172 rests on a special pedestal on the floor immediately beneath the rack 402, and is only very flexibly connected to the rack 402. Supporting the environmental housing 352 on the special pedestal minimizes vibration, etc. and thermally couples the environmental housing 352 to the floor to enhance its thermal regulation.

Portcard

Mounted in the rack 402 above the environmental housing 352 are numerous duplex sockets 404 included in portcards 406 that are adapted to receive duplex pairs of optical fibers 106. One optical fiber 106 of a duplex pair brings one beam of light 108 to the fiber optic switch 400 and another receives one beam of light 108 from the fiber optic switch 400. The portcards 406 are arranged either horizontally or vertically within the rack 402, and can be individually removed or installed without interfering with immediately adjacent portcards 406. As is a common practice in the telecommunications industry, the portcards 406 are hot swappable. The reflective switching module 100 may contain spare mirror surfaces 116 so the fiber optic switch 400 can retain its full operating capability if a few of the mirror surfaces 116 were to fail. It is readily apparent that, in principle, all or any lesser number of the optical fibers 106 connected to a portcard 406 may receive a beam of light 108 therefrom. Similarly, all or any lesser number of the optical fibers 106 connected to a portcard 406 may carry a beam of light 108 to the portcard 406. The optical fibers 106 may be organized in duplex pairs as illustrated in FIG. 26, but need not be so organized.

In the block diagram of FIG. 26, all items to the left of a dashed line 412 are included in the portcard 406, and all items to the right of a dashed line 414 are included in the reflective

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5 switching module 100. The area between the dashed lines 412 and
414 illustrates a backplane of the rack 402. Each portcard 406
includes electronics, alignment optics and electro-optics
10 required to control operation of a portion of the reflective
5 switching module 100. Thus, all of the optical fibers 106
included in the reflective switching module 100 connect to a
portcard 406. Similarly, all of the torsional scanners 172
15 having mirror surfaces 116 upon which any of the beams of light
108 may impinge connect via its substrate 212 and a ribbon cable
10 226 to a portcard 406. Each portcard 406 preferably, but not
necessarily, connects to sixteen (16) or thirty-two (32) optical
20 fibers 106, one-half of which it is envisioned may be receiving
a beam of light 108 from the portcard 406 and one-half that may
be carrying a beam of light 108 to the portcard 406. In FIG. 26
15 the odd number subscripted optical fibers $106_1, 106_3, \dots 106_{2n-1}$
carry a beam of light 108 to the reflective switching module 100
25 while the even number subscripted optical fibers $106_2, 106_4,$
 $\dots 106_{2n}$ carry a beam of light 108 from the reflective
switching module 100.

20 The portcard 406 includes light sources 422 and taps or
directional couplers 424 for supplying and coupling light into
the optical fiber 106 for use in servo alignment of the reflec-
tive switching module 100. The directional couplers 424 also
30 supply light received from the reflective switching module 100
35 via optical fibers 106 to light detectors 426. The portcard 406
also includes driving, sensing and control electronics 432, e.g.
a digital signal processor ("DSP") together with its associated
circuits, which exchange electrical signals via the ribbon cables
40 226 with the electrodes 214 included in the substrates 212 and
30 with the torsion sensors 192a and 192b included in each of the
torsional scanners 172 mounted on the substrates 212. The
driving, sensing and control electronics 432 controls the
45 orientation of mirror surfaces 116 including implementing servo
loops that ensure their proper orientation, and also communicates
35 with the supervisory processor 436 through an RS232 data
communication link 438.

50 The backplane between dashed lines 412 and 414 includes
connections for the optical fibers 106 to the portcards 406,

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preferably multifiber connectors for single mode, optical fiber ribbon cables that connect, for example, 12, 16 or more optical fibers 106. The backplane between dashed lines 412 and 414 also includes connectors 442 for all the ribbon cables 226, the data communication link 438 and other miscellaneous electrical connections such as electrical power required for operation of the driving, sensing and control electronics 432.

In orienting a pair of mirror surfaces 116, one in each of the sets 118a and 118b, to couple one beam of light 108 between one optical fiber 106 at side 102a and another at side 102b, the two mirror surfaces 116 are initially oriented appropriately using pre-established angular coordinates which specify rotations about two (2) axes for each mirror surface 116 in the pair. Thus, for an $N \times N$ reflective switching module 100 and ignoring any spare mirror surfaces 116 included in the reflective switching module 100, the fiber optic switch 400 must store $4 \times N^2$ values for orientation signals produced by the torsion sensors 192a and 192b included in each torsional scanner 172. Accordingly, the reflective switching module 100 includes a look-up table 452, illustrated in FIG. 27a that is maintained in the supervisory processor 436, that stores the $4 \times N^2$ values for orientation signals for use at any time during the operating life of the fiber optic switch 400.

The $4 \times N^2$ values for orientation signals produced by the torsion sensors 192a and 192b included in each torsional scanner 172 may be initially determined analytically. During assembly of the fiber optic switch 400, the analytically determined coordinates and orientation signals are fine tuned to accommodate manufacturing tolerances, etc. Furthermore, throughout the operating life of the fiber optic switch 400 these coordinates and orientation signals may be updated when necessary. Accordingly, the look-up table 452 stores compensation data for initial values of the coordinates and orientation signals, e.g. sensor offsets and temperature compensation since the temperature coefficient of the torsion sensors 192a and 192b is well characterized.

In a preferred embodiment of the fiber optic switch 400, a higher frequency servo system uses the orientation signals

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5 produced by the torsion sensors 192a and 192b in controlling
orientation of each mirror surface 116. The frequency response
of this higher frequency servo system permits accurate orienta-
10 tion of pairs of mirror surfaces 116 when switching from one
5 pairing of optical fibers 106 to another pairing. The higher
frequency servo system also maintains orientation of all mirror
surfaces 116 despite mechanical shock and vibration. To ensure
15 precise orientation of pairs of mirror surfaces 116 during
operation of the fiber optic switch 400, the fiber optic switch
10 400 also employs lower frequency optical feedback servo described
in greater detail below.

20 In initially orienting a pair of mirror surfaces 116, one
in each of the sets 118a and 118b, to couple one beam of light
108 between one optical fiber 106 at side 102a and another at
15 side 102b, stored values for orientation signals are transmitted
from the look-up table 452 respectively to two dual axis servos
25 454 that are included in the portcards 406 for each torsional
scanner 172 which exchanges signals with the portcard 406. Each
dual axis servo 454 transmits driving signals via the ribbon
20 cable 226 to the electrodes 214 included in the substrates 212
to rotate the mirror surfaces 116 to pre-established orienta-
30 tions. The two torsion sensors 192a and 192b included in each
torsional scanner 172 transmit their respective orientation
signals back to the respective dual axis servos 454 via the
35 ribbon cable 226. The dual axis servos 454 respectively compare
the orientation signals received from their associated torsion
sensors 192a and 192b with the values for orientation signals
received from the look-up table 452. If any difference exists
40 between the stored values for orientation signals received from
the look-up table 452 and the orientation signals which the dual
axis servos 454 receive from their respective torsion sensors
192a and 192b, then the dual axis servos 454 appropriately
45 correct the driving signals which they transmit to the electrodes
214 to reduce any such difference.

35 FIG. 27b depicts one of two identical channels, either
x-axis or y-axis, of the dual axis servos 454. As depicted in
50 that FIG. and as described above, a current source 462, included
in the portcard 406, supplies an electric current to the series

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5 connected torsion sensors 192a and 192b of the torsional scanner 172. Differential output signals from one or the other of the torsion sensors 192a and 192b, in the illustration of FIG. 27 the X-axis torsion sensor 192b, are supplied in parallel via the
10 ribbon cable 226 to inputs of an instrumentation amplifier 463 also included in the portcard 406. The instrumentation amplifier 463 transmits an output signal that is proportional to the signal produced by the X-axis torsion sensor 192b to an input of an
15 error amplifier 464.

10 As described above, the driving, sensing and control electronics 432 of the portcard 406 includes a DSP 465 which executes a computer program stored in a random access memory ("RAM") 466. Also stored in the RAM 466 are values for orientation signals which specify an orientation for the mirror surface
20 116 that have been supplied from the look-up table 452 maintained at the supervisory processor 436. The computer program executed by the DSP 465 retrieves the angular coordinate, either X-axis or Y-axis as appropriate, and transmits it to a digital-to-analog converter (DAC) 467. The DAC 467 converts the angular coordinate
25 received from the DSP 465 in the form of digital data into an analog signal which the DAC 467 transmits to an input of the error amplifier 464.

30 An output of the error amplifier 464 transmits a signal to an input of an integrator circuit 472 that is proportional to the difference between the analog signal representing the angular coordinate and the signal from the instrumentation amplifier 463 that is proportional to the signal produced by the X-axis torsion sensor 192b. The integrator circuit 472, consisting of an
35 amplifier 473 and a network of resistors 474 and capacitors 475, transmits an output signal directly to an input of a summing amplifier 476a, and to an input of an inverting amplifier 477. The inverting amplifier 477 transmits an output signal to an
40 input of a second summing amplifier 476b. In addition to the signals respectively received directly from the integrator circuit 472 and indirectly from the integrator circuit 472 via the inverting amplifier 477, inputs of the summing amplifiers
45 476a and 476b also receive a fixed bias voltage. The summing amplifiers 476a and 476b respectively transmit output signals,

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5 which are proportional to a sum of their respective input
signals, to inputs of a pair of high voltage amplifiers 478. The
high voltage amplifiers 478 respectively transmit driving signals
10 via the ribbon cable 226 either to the X-axis or to Y-axis
5 electrodes 214 of the torsional scanner 172.

In this way the dual axis servos 454 supply differential
drive signals to the electrodes 214 of the torsional scanner 172
15 which respectively are symmetrically greater than and less than
a voltage established by the bias voltage supplied to the summing
10 amplifiers 476a and 476b. Furthermore, the drive signals which
the dual axis servos 454 supply to the electrodes 214 are
20 appropriately corrected to reduce any difference that might exist
between the output signals from the torsion sensors 192a and 192b
and the values for orientation signals specified in the look-up
15 table 452.

Since single crystal silicon at room temperatures does not
25 undergo plastic deformation, is dislocation free, has no losses,
and does not exhibit fatigue, the mechanical characteristics of
torsional flexure hinges 176 and 182 made from that material
20 remain stable for years. Consequently, a combination of the long
30 term stability of the torsional flexure hinges 176 and 182 and
the torsion sensors 192a and 192b assure that the values for
orientation signals which the look-up table 452 supplies to the
pair of dual axis servos 454 will effect almost precise alignment
35 of pairs of mirror surfaces 116.

However, as is disclosed in the '463 and the '153 patents,
inclusion of an optical servo loop in a fiber optic switch
40 ensures precise alignment. To permit implementing such an
optical servo loop, as depicted in FIG. 26 each portcard 406
30 included in the fiber optic switch 400 includes one directional
coupler 424 for each optical fiber 106 together with one light
detector 426. Each directional coupler 424 couples approximately
45 5% to 10% of light propagating through one optical fiber included
in the directional coupler 424 into another optical fiber with
35 95% to 90% of that light remaining in the original optical fiber.
Consequently, if a light source 422 is turned-on 5% to 10% of the
50 light emitted by the light source 422 into the directional
coupler 424 passes into an incoming optical fiber 106, e.g.

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5 optical fiber 106₁, for transmission onto the reflective
switching module 100 together with 95% to 90% of any other light
that is already propagating along the optical fiber 106 toward
10 the reflective switching module 100. The reflective switching
5 module 100 couples this combined light from the incoming optical
fiber 106, e.g. optical fiber 106₁, into an outgoing optical
fiber 106, e.g. optical fiber 106₂. Upon reaching the direction-
15 al coupler 424 associated with the outgoing optical fiber 106,
e.g. optical fiber 106₂, 5% to 10% of the light received from the
10 reflective switching module 100 passes from the optical fiber 106
through the directional coupler 424 to the light detector 426
20 connected to that directional coupler 424. If necessary, the
fiber optic switch 400 exploits the ability to introduce light
into the optical fiber 106 for transmission through the reflec-
15 tive switching module 100 and then recovering a fraction of the
transmitted light to analyze and adjust the operating state of
25 specific pairs of mirror surfaces 116, and to ensure precise
alignment of pairs of mirror surfaces 116 during operation of the
fiber optic switch 400.

20 In considering operation of this optical servo portion of
the fiber optic switch 400, it is important to note that the
optical servo aligns a pair of mirror surfaces 116 regardless of
the direction in which alignment light propagates through the
pair of mirror surfaces 116, i.e. from incoming optical fiber 106
35 25 to outgoing optical fiber 106 or conversely. Consequently, in
principle the portcards 406 need equip only one-half of the
optical fibers 106 included in the fiber optic switch 400, e.g.
all the incoming optical fibers 106 or all the outgoing optical
40 fibers 106, with the light source 422. However, to facilitate
30 flexible and reliable operation of the fiber optic switch 400 in
a telecommunication system all of the directional couplers 424,
both those connected to incoming and to outgoing optical fibers
45 106, may, in fact, be equipped with the light source 422.

Referring now to FIG. 26a, an output from every directional
35 coupler 424 of the portcard 406 supplies light to a
telecom-signal-strength photo-detector 482. Every
50 telecom-signal-strength photo-detector 482 receives and responds
to a fraction of light propagating into the reflective switching

5 module 100 along the optical fibers 106 regardless of whether the
optical fiber 106 is an incoming or an outgoing optical fiber
106. Thus, before a pair of mirror surfaces 116 are precisely
10 aligned optically, output signals from two
5 telecom-signal-strength photo-detectors 482 indicate whether
portcard 406 must supply light from the light source 422 for that
purpose, or whether the incoming optical fiber 106 carries a
15 telecommunication signal of sufficient strength to permit optical
alignment. If the signals from the pair of
10 telecom-signal-strength photo-detectors 482 indicate that neither
of the two optical fibers 106 carry sufficient light to perform
optical alignment, then the portcard 406 turns-on the light
20 source 422 to obtain light required for optical alignment,
otherwise light present on the incoming optical fiber 106 is used
15 for that purpose.

25 One approach for using light introduced into the optical
fiber 106 from the light source 422 illustrated in FIG. 26a
envisions using 850 nm light from a relatively inexpensive laser
diode for the light source 422. In this approach, an
20 alignment-light detector 484 that is sensitive to red wavelengths
of light may be an inexpensive silicon photo-detector. However,
in addition to light generated by the light source 422 at 850 nm,
the incoming optical fiber 106 may also be concurrently carrying
light at optical telecommunication wavelengths, e.g. 1310 A° or
35 1550 A°, which perhaps has greater power than that generated by
the light source 422. To ensure separation of the 850 nm
alignment light generated by the light source 422_{2j-1} and supplied
to the reflective switching module 100 via optical fiber 106_{2j-1}
40 from light at optical telecommunication wavelengths, the output
30 of the directional coupler 424 which emits a portion of the light
received by the portcard 406 from the reflective switching module
100 directs such light onto a dichroic mirror 486_{2j}. The
45 dichroic mirror 486_{2j} reflects the 850 nm alignment light to the
alignment-light detector 484 while permitting light at optical
35 telecommunication wavelengths to pass onto a
telecom-signal-monitoring photo-detector 488. If the reflective
switching module 100 is to be fully bidirectional so any optical
50 fiber 106 may at any instant be an incoming or an outgoing

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5 optical fiber 106, then a dichroic mirror 486_{2j-a} must be used
with the directional coupler 424_{2j-1} to separate light from the
light source 422_{2j-1} from light at optical telecommunication
10 wavelengths that the telecom-signal-monitoring photo-detector
5 488_{2j-1} receives.

For several reasons after the pair of mirror surfaces 116
have been initially precisely aligned optically to establish a
15 connection via the reflective switching module 100 between an
incoming optical fiber 106 and an outgoing optical fiber 106, it
10 appears advantageous to turn-off the light source 422 and to use
light coming to the fiber optic switch 400 at optical telecommu-
20 nication wavelengths in periodically checking alignment. The
configuration of the light source 422 and light detector 426
remains as depicted in FIG. 26a. Operating in this way, the
15 telecom-signal-strength photo-detector 482 which first receives
light at optical telecommunication wavelengths coming into the
25 fiber optic switch 400 via the duplex sockets 404 detects loss
of light or loss of modulation in incoming light. During such
operation of the fiber optic switch 400, the
20 telecom-signal-monitoring photo-detectors 488 are used in
conjunction with the telecom-signal-strength photo-detectors 482
for periodically monitoring and maintaining the quality of light
transmission through the reflective switching module 100. Tests
35 have demonstrated that the orientation signals from the torsion
25 sensors 192a and 192b supplied to the dual axis servo 454
maintain adequate alignment of the mirror surfaces 116 for
extended period of time, e.g. hours. Consequently, after a pair
of mirror surfaces 116 have been precisely aligned optically only
40 relatively infrequent adjustment of the mirror orientation is
30 required to compensate for drift in the torsion sensors 192a and
192b, temperature changes, mechanical creep of the reflective
switching module 100 including the support frames 224 and perhaps
45 the substrates 212, etc.

In an alternative approach for detecting alignment light
35 supplied from the light source 422 at 850 nm, the dichroic mirror
486_{2j} and its associated photo-detectors 484 and 488 may be
50 replaced by a compound sandwich photo-detector, illustrated in
FIG. 26b. In the compound sandwich detector illustrated there,

5 a silicon photo-detector 492 is mounted over a long wavelength
photo-detector 494 such as germanium (Ge) or indium gallium
10 arsenide (InGaAs) photo-detector. The compound sandwich photo-
5 detector absorbs the shorter alignment wavelength in the silicon
photo-detector 492. However, longer wavelengths of the optical
telecommunications light pass virtually un-attenuated through the
15 silicon photo-detector 492 to be absorbed in the long wavelength
photo-detector 494. Use of the compound sandwich photo-detector
fully separates the two signals. The InGaAs photo-detector may
20 be replaced by a second Ge photo-detector to detect the longer
wavelength light, but with less sensitivity than the InGaAs
photo-detector. However, a difficulty associated with using
light at 850 nm for alignment is that the directional couplers
25 424 become multi-mode devices so the fraction of the alignment
light being coupled into and out of the optical fiber 106 varies
over time.

To avoid difficulties associated with using 850 nm light for
precisely aligning a pair of mirror surfaces 116 optically, it
is also possible and advisable to supply light at optical
30 telecommunication wavelengths, e.g. 1310 Å or 1550 Å, from the
light source 422. Light at these wavelengths may be provided by
an inexpensive vcsel. While vcsels lack the precise wavelength
or stability of expensive laser sources of such light, the
precision and stability provided by laser sources are not
35 required for optically aligning a pair of mirror surfaces 116.
Using light at optical telecommunication wavelengths has the
advantage that the and the alignment-light detector 484 may be
eliminated, and that the coupling coefficient for the directional
40 couplers 424 are higher and more stable than for 850 nm light.
Therefore, a vcsel need supply less light or power for optical
30 alignment than a laser diode producing 850 nm light.

If initial optical alignment of pairs of mirror surfaces 116
45 requires using an expensive laser that generates light at optical
telecommunication wavelengths for the light source 422, the cost
35 of that source may be shared among directional couplers 424 using
a 1×N optical switch. Such a 1×N optical switch may be very
50 large to provide light to all the portcards 406. Alternatively,
to enhance reliability the fiber optic switch 400 might include

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several such optical telecommunication lasers with a smaller 1xN optical switches each one of which provides light to only the directional couplers 424 included in a single portcard 406.

5 Optical Beam Alignment

Including the fiber optic switch 400 in a telecommunications network makes reliability and availability of utmost importance. Therefore, it is extremely important that the mirror surfaces 116 are always under control of the dual axis servos 454, that initially forming a connection which couples light from one optical fiber 106 to another optical fiber 106 via the reflective switching module 100 be precise, and that the quality of the coupling be maintained while the connection persists. As described above in connection with FIGs. 26 and 26a, all the portcards 406 provide a capability for monitoring the precise alignment of pairs of mirror surfaces 116 either with light incoming to the fiber optic switch 400 or with light generated by one of the light sources 422.

The fiber optic switch 400 exploits the capability of the portcards 406 to facilitate optical alignment of pairs of mirror surfaces 116 by monitoring the quality of coupling between pairs of optical fibers 106 connected to the reflective switching module 100. In monitoring the quality of that coupling, the fiber optic switch 400 tilts slightly each mirror surface 116 in a pair from the orientation specified by the values for orientation signals stored in the look-up table 452, i.e. dithering both mirror surfaces 116, while concurrently monitoring the strength of the beam of light 108 coupled between the two optical fibers 106. Because, in general, monitoring the strength of the beam of light 108 coupled between two optical fibers 106 requires coordination between two of the at least thirty-six (36) portcards 406 included in the fiber optic switch 400, that process must at least be supervised by the supervisory processor 436 illustrated in FIG. 26. Accordingly, whenever it is necessary or helpful to optically align a pair of mirror surfaces 116 the supervisory processor 436 sends appropriate commands to the DSP 465 included in each of the involved portcards 406, illustrated in FIG. 27b, via the data communication link 438 and

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5 a RS232 port 502 included in each of the portcards 406. The
commands sent by the supervisory processor 436 cause the DSP 465
to send coordinate data to the two DACs 467 included in the dual
10 axis servo 454 which tilts slightly the mirror surface 116 whose
5 orientation the dual axis servo 454 controls. Because this
change in orientation changes the impingement of the beam of
light 108 on the lens 112 associated with the outgoing optical
15 fiber 106, the amount of light coupled into the associated
optical fiber 106 changes. This change in the light coupled into
10 the optical fiber 106 is coupled through the directional coupler
424 through which the outgoing light passes to the light detector
426 included in that portcard 406. To permit detecting this
20 change of light, the computer program executed by the DSP 465
acquires light intensity data from an analog-to-digital converter
15 ("ADC") 504 that is coupled to the light detector 426 as
illustrated in FIG. 27b. The fiber optic switch 400, either in
25 the DSP 465 on the portcard 406 or in the supervisory processor
436, or in both, analyzes this light intensity data to precisely
align the two mirror surfaces 116 for coupling the beam of light
20 108 between the two optical fibers 106.

30 After the mirror surfaces 116 have been precisely aligned
optically, the fiber optic switch 400 confirms that light from
the incoming optical fiber 106 is being coupled through the
reflective switching module 100 to the proper outgoing optical
35 fiber 106 by dithering only the mirror surface 116 upon which the
incoming beam of light 108 first impinges. If the reflective
switching module 100 has been properly aligned to couple light
between a specified pair of optical fibers 106, the intensity
40 modulation of light from the incoming beam of light 108 caused
30 by dithering this particular mirror surface 116 must appear in
only the correct outgoing optical fiber 106, and in no other
optical fiber 106.

45 After the pair of mirror surfaces 116 have been optically
aligned as described above, and after confirming that incoming
35 light is being coupled through the reflective switching module
100 into the proper optical fiber 106, the fiber optic switch 400
50 periodically monitors the quality of the connection using the
ability to dither the orientation of the mirror surfaces 116.

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5 The computer program executed by the supervisory processor 436
as appropriate uses the alignment data acquired in this way for
updating the angular coordinate data stored in the look-up table
10 452, and may also preserve a log of such data thereby permitting
5 long term reliability analysis of fiber optic switch 400.

Industrial Applicability

15 FIG. 28a shows an alternative embodiment structure for
receiving and fixing optical fibers 106 that may be used at the
10 sides 102a and 102b instead of the convergence block 152 and the
optical fiber collimator assemblies 134. In the structure
20 depicted in FIG. 28a, a clamping plate 602, micromachined from
silicon, secures the optical fibers 106. An adjustment plate
604, also micromachined from silicon, permits adjusting the ends
15 104 of the optical fibers 106 that protrude therethrough both
from side-to-side and up-and-down, and then fixing the ends 104
25 in their adjusted position. The clamping plate 602 is pierced
by an array of holes 606 which are etched through a 1.0 to 2.0
mm thick silicon substrate using the Bosch deep RIE process. The
20 holes 606, which have a diameter only a few microns larger than
the optical fibers 106, typically have a diameter of 100 to 125
microns which matches the outer diameter of typical optical
fibers 106. If the clamping plate 602 must be thicker than 1.0
30 to 2.0 mm, then two or more plates can be juxtaposed and
registered kinematically to each other using V-grooves and rods.
35 After being registered, two or more juxtaposed clamping plates
602 can be glued together.

40 The hole 606 positions the optical fibers 106 precisely with
respect to each other within a few microns. The high depth-to-
30 diameter ratio of the holes 606, e.g. 10:1 or greater, facilitates
fixing the optical fibers 106 longitudinally. To ease
insertion of optical fibers 106 into the holes 606, a pyramiddally
45 shaped entrance 608 to the holes 606, only one of which is
illustrated in FIG. 28a, may be formed on one side of the
35 clamping plate 602 using anisotropic etching.

50 While the holes 606 may be formed as right circular
cylinders, they may also have more complicated cylindrical
profiles such as that illustrated in FIG. 28b. The holes 606 may

5 be RIE or wet etched to provide a profile in which a cantilever
612 projects into the hole 606. The cantilever 612 is positioned
with respect to the remainder of the hole 606 so that insertion
10 of the optical fiber 106 thereinto bends the cantilever 612
5 slightly. In this way the cantilever 612 holds the optical fiber
106 firmly against the wall of the hole 606 while permitting the
optical fiber 106 to slide along the length of the hole 606. The
15 holes 606 may incorporate other more complicated structures for
fixing the optical fiber 106 with respect to the holes 606. For
10 example, a portion of each hole 606 may be formed with the
profile depicted in FIG. 28b while the remainder, etched in
registration from the opposite side of the clamping plate 602,
20 may be shaped as a right circular cylinder.

After the clamping plate 602 has been fabricated, optical
15 fibers 106 are inserted through all the holes 606 until all the
optical fibers 106 protrude equally a few millimeters, e.g. 0.5
25 to 3.0 mm, out of the clamping plate 602. Protrusion of the
optical fibers 106 this far beyond the clamping plate 602 permits
easily bending them. Identical protrusion of all the optical
20 fibers 106 may be ensured during assembly by pressing the ends
104 of the optical fibers 106 against a stop. The optical fibers
106 may be fixed to the clamping plate 602 by gluing, soldering,
or simply be held by frictional engagement with the cantilever
30 612.

35 25 The adjustment plate 604, best illustrated in FIG. 28c,
includes an array of XY micro-stage stages 622 also etched
through a 1.0 to 2.0 mm thick silicon substrate using the Bosch
deep RIE process. Each XY micro-stage 622 includes a hole 624
40 adapted to receive the end 104 of the optical fiber 106 that
30 projects through the clamping plate 602. The distances between
holes 624 piercing the adjustment plate 604 are identical to
those which pierce the clamping plate 602, and may be formed with
45 the profile depicted in FIG. 28b. Each optical fiber 106 fits
snugly within the hole 624.

35 FIG. 29 a depicts in greater detail one of the XY
micro-stage stages 622 included in the adjustment plate 604. An
50 analogous monolithic silicon XY stage is described in United
States Patent no. 5,861,549 ("the '549 patent") that issued

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January 19, 1999. FIG 29a illustrates that the entire XY micro-stage 622 is formed monolithically from a silicon substrate using RIE etching. An outer base 632, that encircles the XY micro-stage 622, is coupled to an intermediate Y-axis stage 634 by four (4) flexures 636 of a type described by Teague et al in, Rev. SCI. Instrum., 59, pg. 67, 1988. Four similar flexures 642 couple the Y-axis stage 634 to a X-axis stage 644. The flexures 636 and 642 are of the paraflex type and therefore stretch adequately for the XY motion envisioned for the hole 624. The XY micro-stage 622 need only to be able to move and position the ends 104 of the optical fibers 106 over small distances which avoids undue stress on the flexures 636 and 642. Other configurations for the flexures 636 and 642, similar to those described in the '549 patent, may also be used.

The XY micro-stage 622 likely omits any actuators, but the Y-axis stage 634 may be fixed in relation to the outer base 632 with a metal ribbon, e.g. gold, kovar, tungsten, molybdenum, aluminum, or wire linkage 652. Similarly, the X-axis stage 644 may be fixed in relation to the Y-axis stage 634 also with a metal ribbon or wire linkage 654. The material chosen for the linkages 652 and 654 preferably has a coefficient of expansion the same as or close to that of silicon. However, if the linkages 652 and 654 are short, e.g. 100 microns, then even for a 20 PPM differential coefficient of expansion between the silicon and the metal (e.g. aluminum), the movement of the X-axis stage 644 with respect to the outer base 632 would only be approximately 20 Å° per degree Celsius. Metals other than aluminum provide even greater thermal stability.

In adjusting the XY micro-stage 622, the linkages 652 and 654 are first bonded respectively to the Y-axis stage 634 and to the X-axis stage 644. By pulling the metal linkages 652 and 654 simultaneously while viewing the end 104 of the optical fiber 106 through a microscope, the X-axis stage 644 may be moved along both the X and Y axes to position the end 104 at a specified location. After the X-axis stage 644 has been move to properly position the end 104, the linkages 652 and 654 are bonded or spotwelded in place.

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5 The XY micro-stage 622 may include a lever 622 illustrated
in FIG. 29c to reduce movement of the X-axis stage 644 in
comparison with movement of a distal end 664 of the XY
10 micro-stage 622. For the XY micro-stage 622 illustrated in that
5 FIG., etching to form the stages 634 and 644 also yields the
lever 622 that is cantilevered from the Y-axis stage 634. The
linkage 654 is initially bonded both to the X-axis stage 644 and
15 to the lever 622. A similar linkage 666 is fastened to the end
of the lever 622 distal from its juncture with the Y-axis stage
10 634. After the X-axis stage 644 has been move to properly
position the end 104, as before the linkage 666 is bonded or
spotwelded to the Y-axis stage 634. Alternatively, as illustrat-
20 ed in FIG. 29c, the linkage 654 may be omitted from the XY
micro-stage 622 to be replaced by a flexible pushpin 672, well
15 known in the art, that couples between the X-axis stage 644 and
the lever 622 cantilevered from the Y-axis stage 634. Opposite
25 ends of the flexible pushpin 672 are coupled by flexures 674
respectively to the X-axis stage 644 and to the lever 622. The
embodiment of the XY micro-stage 622 depicted in FIG. 29c
20 requires only one linkage 666 for fixing the X-axis stage 644
when the end 104 of the optical fiber 106 is at its specified
location. Furthermore, the movement of the X-axis stage 644 is
now bi-directional because the flexible pushpin 672 can both push
and pull on the X-axis stage 644.

35 25 While the preceding description of the lever 622 has
addressed only X-axis motion of the X-axis stage 644, it is
readily apparent that a similar lever could be incorporated into
the outer base 632 for effecting Y-axis motion of the Y-axis
40 stage 634 and of the X-axis stage 644 with respect to the outer
30 base 632.

As described above, the XY micro-stage 622 permits fixing
and adjusting the ends 104 of optical fibers 106 along their X
45 and Y axes. However, properly focusing the lens 112 with respect
to the ends 104 of optical fibers 106 may require relative
35 movement either of the end 104 or the lens 112 along the
longitudinal axis 144. The separation between the end 104 of
50 optical fiber 106 and the lens 112 may be adjusted in various
different ways. Bright, et al., SPIE Proc., vol. 2687, pg.34,

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5 describe a poly-silicon mirror, moving like a piston, which may be electrostatically displaced perpendicular to the substrate upon which it has been fabricated.

10 FIG. 30a depicts a monolithic plano-convex lens 112
5 micromachined from a SOI wafer 162 using RIE etching that can be electrostatically displaced along the longitudinal axis 144 perpendicular to the substrate upon which it was been fabricated.
15 To permit electrostatically displacing the lens 112 along the longitudinal axis 144, as illustrated in FIG. 30b the lens 112
10 is supported from the surrounding device silicon layer 166 of the wafer 162 by three (3) V-shaped flexures 682. One end of the flexures 682, each of which extends part way around the periphery
20 of the lens 112, is coupled to the surrounding device silicon layer 166 while the other end is coupled to the lens 112. Except
15 for deflection electrodes 684 that are disposed to the right of the lens 112 in FIG. 30a and electrically insulated from the
25 wafer 162, the entire assembly is made as one monolithic silicon structure. Electrostatic attraction between the electrodes 684 and the combined flexures 682 and the lens 112, created by
30 applying an electrical potential between the electrodes 684 and the device silicon layer 166, pulls the lens 112 toward the electrodes 684 along the longitudinal axis 144.

35 Silicon lenses suitable for IR optical fiber transmission are commercially available and may be adapted for use in this
25 invention. Accordingly, small individual commercially available micro-lenses may be placed into a cavity etched into a flat membrane supported by the flexures 682. Alternatively, the lens 112 may be formed using RIE while the flexures 682 are being
40 formed. Yet another alternative is to first diamond turn the lens 112 and then protect it from etching while the flexures 682
30 are formed using RIE. Still another alternative is to first form the flexures 682 using RIE while protecting the area where the lens 112 is to be formed, and then diamond turning the lens 112.
45 After the lens 112 and the flexures 682 have been formed in any
35 of these ways, the wafer 162 underlying them is removed with anisotropic etching to expose the silicon dioxide layer 164. The
50 backside 170 of the lens 112 fabricated in this way is optically flat.

5 Instead of electrostatic actuation, the lens 112 may be moved along the longitudinal axis 144 electro-magnetically. As illustrated in FIG. 30c, the electrodes 684 disposed adjacent to the lens 112 in the illustration of FIG. 30a are replaced with
10 permanent magnets 692 oriented with their magnetic field parallel to the longitudinal axis 144 of the lens 112. Also a coil 694 encircles the lens 112. Electrical leads from the coil 694 are brought out to the device silicon layer 166, preferably symmetrically, via the flexures 682 to ensure linear displacement of the
15 lens 112. Depending upon the direction of current flow applied to the coil 694, the lens 112 moves toward or away from the end 104 of the optical fiber 106.

20 In many telecommunication applications for the fiber optic switch 400, light arriving at the fiber optic switch 400 may have previously passed through a routing wavelength demultiplexer
25 which may typically be in integrated chip form. A significant cost in fabricating routing wavelength demultiplexers is often that of connecting from its planar circuit to outgoing optical fibers. If the reflective switching module 100 of the fiber
30 optic switch 400 described above is properly configured, making connections between the routing wavelength demultiplexer and optical fibers becomes unnecessary. Rather, outgoing beams of light from the routing wavelength demultiplexer are simply coupled in free space to the lenses 112 of the reflective
35 switching module 100 which may include an anti reflection overcoating to reduce reflection.

40 FIG. 31 illustrates an arrangement in which a routing wavelength demultiplexer 702 includes several demultiplexed planar waveguides 704. The demultiplexed planar waveguides 704
30 radiate beams of light 108 directly toward the lenses 112 facing them thereby avoiding any necessity for coupling the routing wavelength demultiplexer 702 to optical fibers. A substrate 706 of the routing wavelength demultiplexer 702, which carries demultiplexed planar waveguides 704, may be placed adjacent to
45 the lenses 112 to supply incoming beams of light 108 to the reflective switching module 100. Likewise where outgoing beams of light 108 leave the reflective switching module 100, the
50 lenses 112 may couple the beams of light 108 directly to

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5 demultiplexed planar waveguides 704 from which the beams of light
may be multiplexed into one or several outgoing optical fibers.
By providing and reserving some extra output and input holes 154
10 in the convergence blocks 152 for use with wavelength converters,
5 the fiber optic switch 400 may provide wavelength conversion for
light received from any optical fiber coupled to the fiber optic
switch 400.

15 Although the present invention has been described in terms
of the presently preferred embodiment, it is to be understood
10 that such disclosure is purely illustrative and is not to be
interpreted as limiting. Consequently, without departing from
20 the spirit and scope of the invention, various alterations,
modifications, and/or alternative applications of the invention
will, no doubt, be suggested to those skilled in the art after
15 having read the preceding disclosure. Accordingly, it is intended
25 that the following claims be interpreted as encompassing all
alterations, modifications, or alternative applications as fall
within the true spirit and scope of the invention.

Claims

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The Claims

What is claimed is:

1. A fiber optic switching module comprising:
a first and a second group of optical fiber receptacles
which are separated from each other at opposite ends of a free
space optical path, and each of which groups is respectively
adapted for receiving and fixing ends of optical fibers;

lenses juxtaposed with ends of optical fibers fixed
respectively at the first and second groups and disposed along
the optical path between groups, each of said lenses being
respectively disposed with respect to an end of an associated
optical fiber of the first or second group so that a beams of
light as may be emitted from the end of the optical fiber pass
through said immediately adjacent lens to propagate as a
quasi-collimated beams through the optical path from said lens
toward said second or first group of optical fiber receptacles;

a first and a second sets of reflective light beam deflec-
tors that are both disposed along the optical path between the
groups of optical fiber receptacles, each of said sets of light
beam deflectors being associated with one of the groups of
optical fiber receptacles and having a number of light beam
deflectors that equals the optical fibers in the group with which
it is associated, each of the light beam deflectors in said first
or said second set:

being associated with one of the optical fibers in the
associated group of optical fiber receptacles;

being located along the optical path so the
quasi-collimated beam of light as may be emitted from the
lens associated with the optical fiber impinges upon the
light beam deflector to be reflected therefrom through the
optical path; and

being energizable by drive signals supplied to said
fiber optic switching module to be oriented for reflecting
the quasi-collimated beam of light as may be emitted from
the associated optical fiber to also reflect off a selected
one of the light beam deflectors in said second or said
first set;

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whereby a pair of light beam deflectors, one light beam deflector of the pair belonging to the first set and one belonging to the second set, may be selected and oriented by the drive signals supplied thereto to couple a quasi-collimated beam of light propagating through the optical path from the end of one optical fiber as may be fixed in the optical fiber receptacle either of the first or of the second group to reflect sequentially off the pair of energized light beam deflectors into a selected one of the optical fiber receptacles so as to enter an optical fiber as may be fixed at the second or at the first group of optical fiber receptacles.

2. The fiber optic switching module of claim 1 wherein the first group of optical fiber receptacles is located at a side A of the fiber optic switching module, and the second group of optical fiber receptacles is located at a side B of the fiber optic switching module, side A being spaced apart from side B; and wherein the first and second sets of light beam deflectors are also spaced apart from each other.

3. The fiber optic switching module of claim 2 wherein the optical path between side A and side B is C-shaped.

4. The fiber optic switching module of claim 2 wherein the optical path between side A and side B is Z-shaped.

5. The fiber optic switching module of claim 2 wherein the optical path between side A and side B is W-shaped.

6. The fiber optic switching module of claim 2 wherein to fold the optical path between said sets of light beam deflectors a mirror is disposed therebetween.

7. The fiber optic switching module of claim 1 wherein to fold the optical path between said sets of light beam deflectors a mirror is disposed therebetween.

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8. The fiber optic switching module of claim 1 wherein the first group includes only one optical fiber receptacle and the second group includes the remaining optical fiber receptacles whereby the fiber optic switching module couples a beam of light from the end of an optical fiber as may be fixed in the one optical fiber receptacle to the end of any optical fiber as may be fixed in the second group of optical fiber receptacles.

9. The fiber optic switching module of claim 1 wherein lenses included in the fiber optic switching module have faces that are oriented at an oblique angle with respect to a longitudinal axis of each lens so beams of light from ends of optical fiber as may be fixed in the optical fiber receptacles emitted at an angle with respect to a center line of the optical fiber become aligned with the longitudinal axis of the lens.

10. The fiber optic switching module of claim 1 wherein lenses included in the fiber optic switching module are formed with a smaller diameter outer surface which is disposed nearer to an end of an optical fiber as may be fixed in one of the optical fiber receptacles, the lenses also being formed with a larger diameter outer surface which is disposed further from an end of an optical fiber as may be fixed in one of the optical fiber receptacles than the smaller diameter outer surface of the lens.

11. The fiber optic switching module of claim 1 wherein individual optical fiber receptacles are conically-shaped and are adapted to receive an individual, mating, conically-shaped optical fiber collimator assembly which carries the lens that is associated with an optical fiber as may be fixed in the optical fiber receptacle, the optical fiber collimator assembly also being adapted for receiving and fixing an end of an optical fiber therein.

12. The fiber optic switching module of claim 11 further comprising environmental housing that encloses the optical path through which the beams of light propagate.

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13. The fiber optic switching module of claim 12 wherein the environmental housing provides temperature regulation for maintaining a stable operating environment for the fiber optic switching module.

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14. The fiber optic switching module of claim 12 wherein dry gas flows through the environmental housing to hinder moisture from condensing within the fiber optic switching module.

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15. The fiber optic switching module of claim 12 wherein the environmental housing is pressurized to exclude atmosphere surrounding the environmental housing from entering the fiber optic switching module.

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16. The fiber optic switching module of claim 12 wherein the environmental housing includes a nonsaturable microdryer to hinder moisture from condensing within the fiber optic switching module.

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17. The fiber optic switching module of claim 12 wherein a wall of the environmental housing is pierced by an electrical feed-through through which the drive signals pass.

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18. A fiber optic switch comprising:

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5 a fiber optic switching module that receives and fixes ends of optical fibers, and that includes a plurality of reflective light beam deflectors which may be selected as pairs to be oriented responsive to drive signals supplied to said fiber optic switching module for coupling a beam of light between a pair of optical fibers fixed in said fiber optic switching module, said fiber optic switching module also producing orientation signals from each light beam deflector which indicate orientation thereof; and

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at least one portcard that supplies the drive signals to said fiber optic switching module for orienting at least one light beam deflector included therein, and which receives the orientation signals produced by that light beam deflector, said

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15 portcard also receiving data which specify an orientation for the
light beam deflector, comparing those received data with the
orientation signals received from the light beam deflector, and
10 adjusting the drive signals supplied to said fiber optic
switching module to reduce any difference between the received
20 data and the orientation signals.

15 19. A portcard adapted for use in a fiber optic switch that
includes an fiber optic switching module that receives and fixes
ends of optical fibers, and that includes a plurality of
reflective light beam deflectors which may be selected as pairs
20 5 to be oriented responsive to drive signals supplied to said fiber
optic switching module for coupling a beam of light between a
pair of optical fibers fixed in said fiber optic switching
module, said fiber optic switching module also producing
orientation signals from each light beam deflector which indicate
25 10 orientation thereof, the portcard comprising:

a driver circuit for supplying the drive signals to said
fiber optic switching module for orienting at least one light
beam deflector included therein; and

30 a dual axis servo that receives data which specify an
15 orientation for the light beam deflector, and also receives the
orientation signals produced by that light beam deflector, the
portcard comparing the data with the orientation signals received
35 from the light beam deflector, and adjusting the drive signals
supplied to said fiber optic switching module to reduce any
20 difference between the received data and the orientation signals.

40 20. The portcard of claim 19 wherein said driver circuit
supplies electrostatic drive signals to said fiber optic
switching module.

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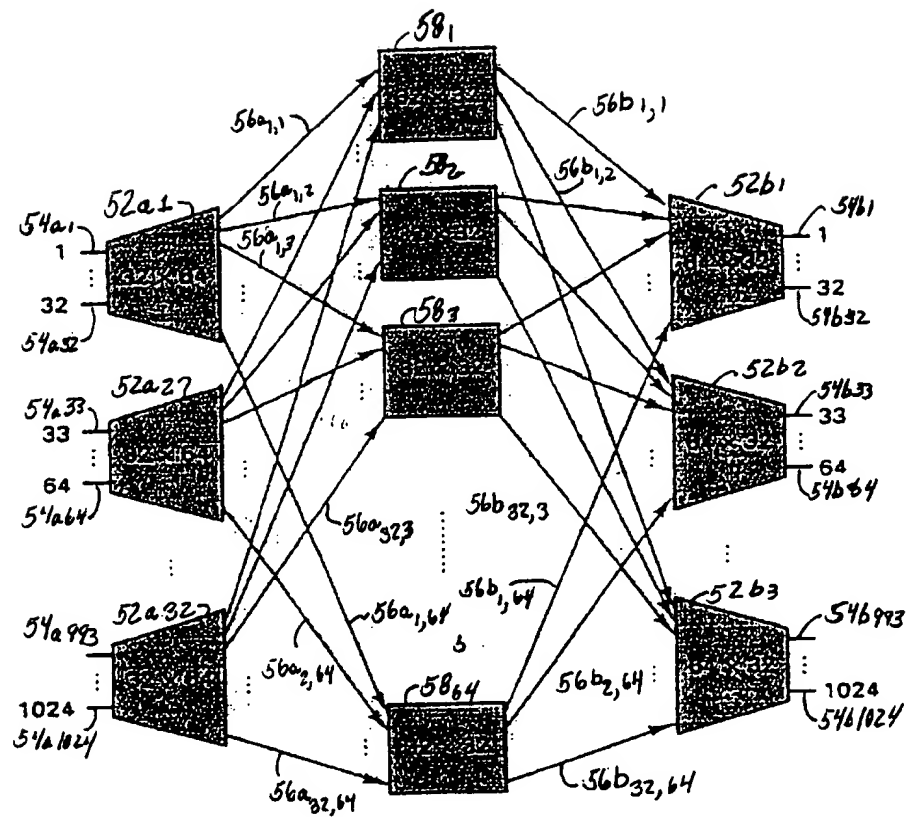
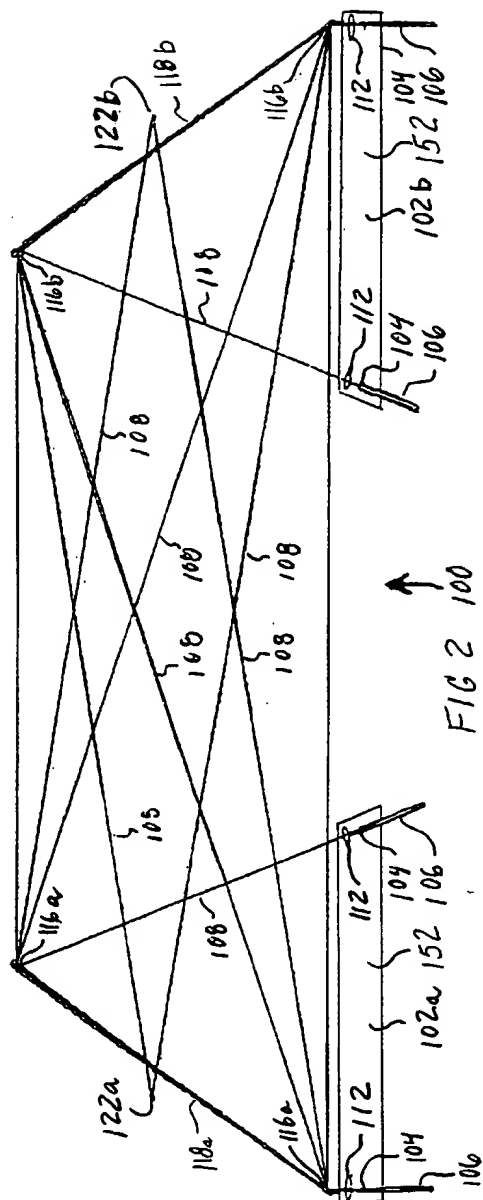


FIG. 1

Prior Art



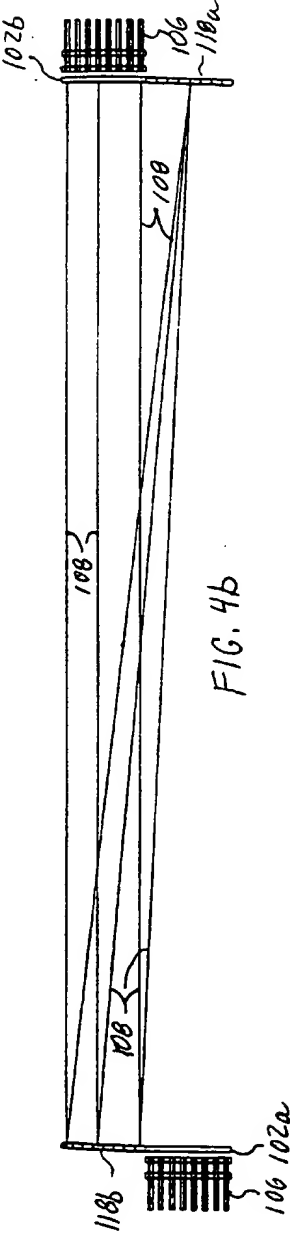


FIG. 4b

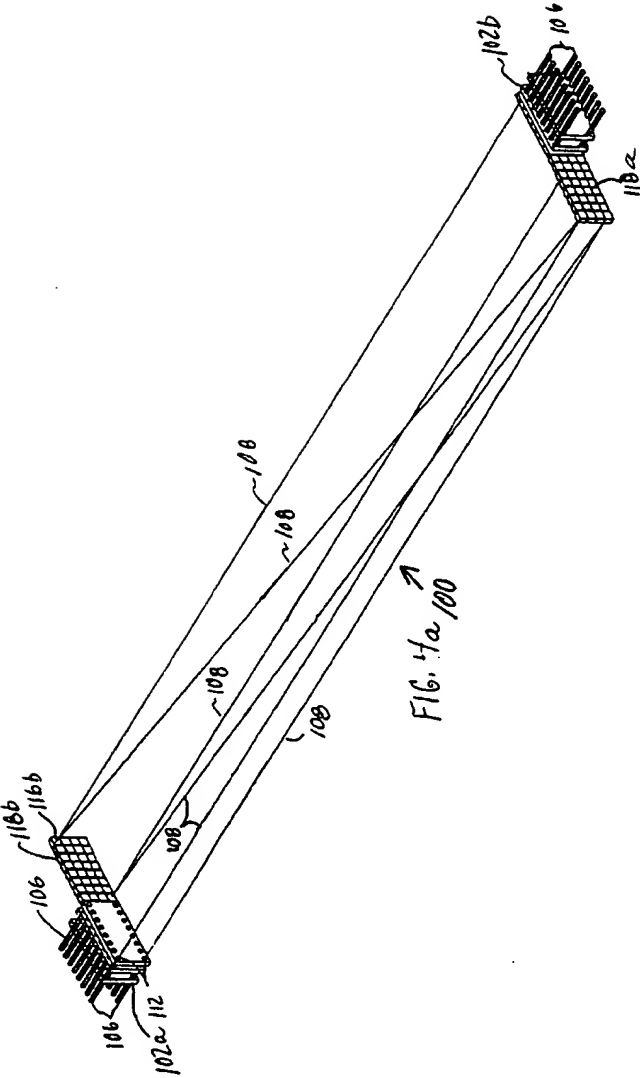
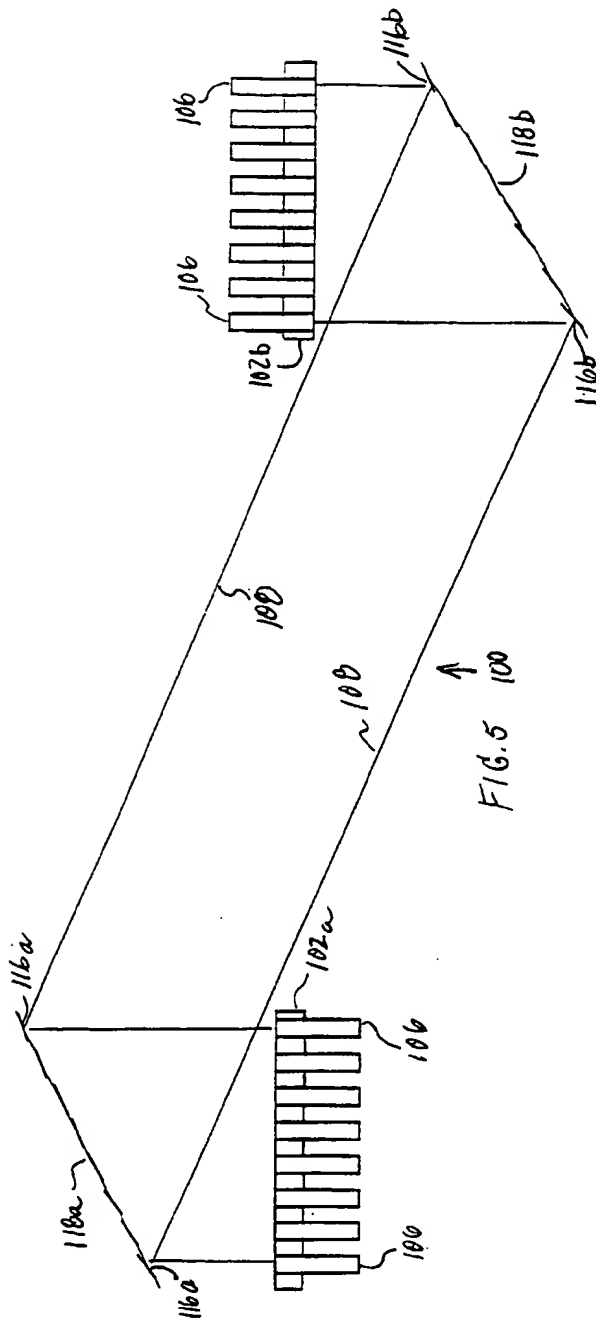
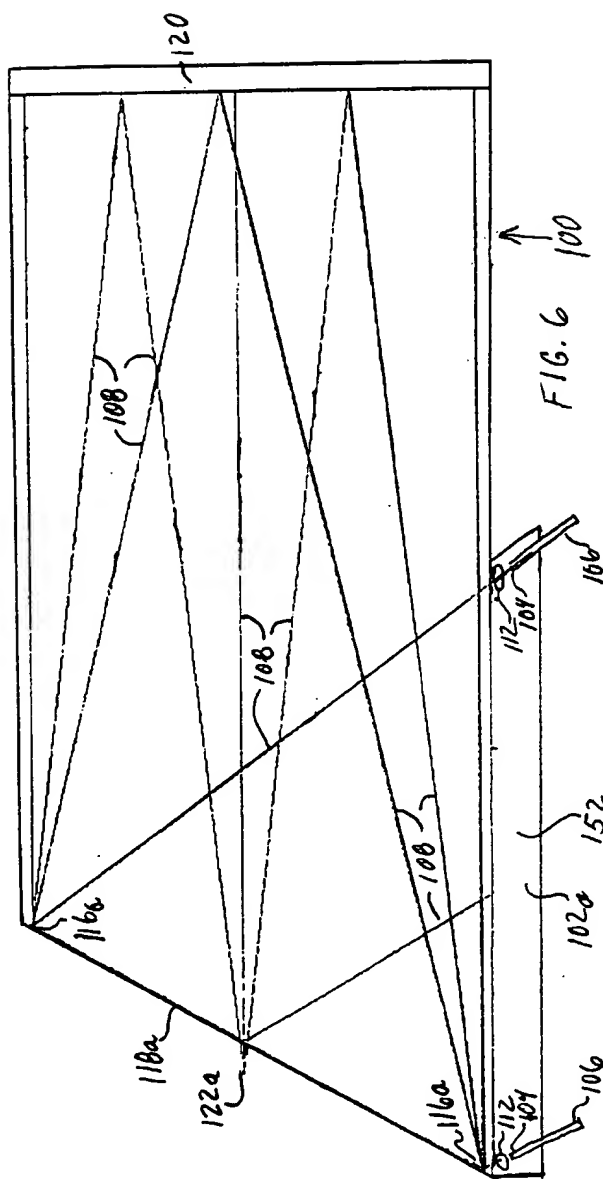
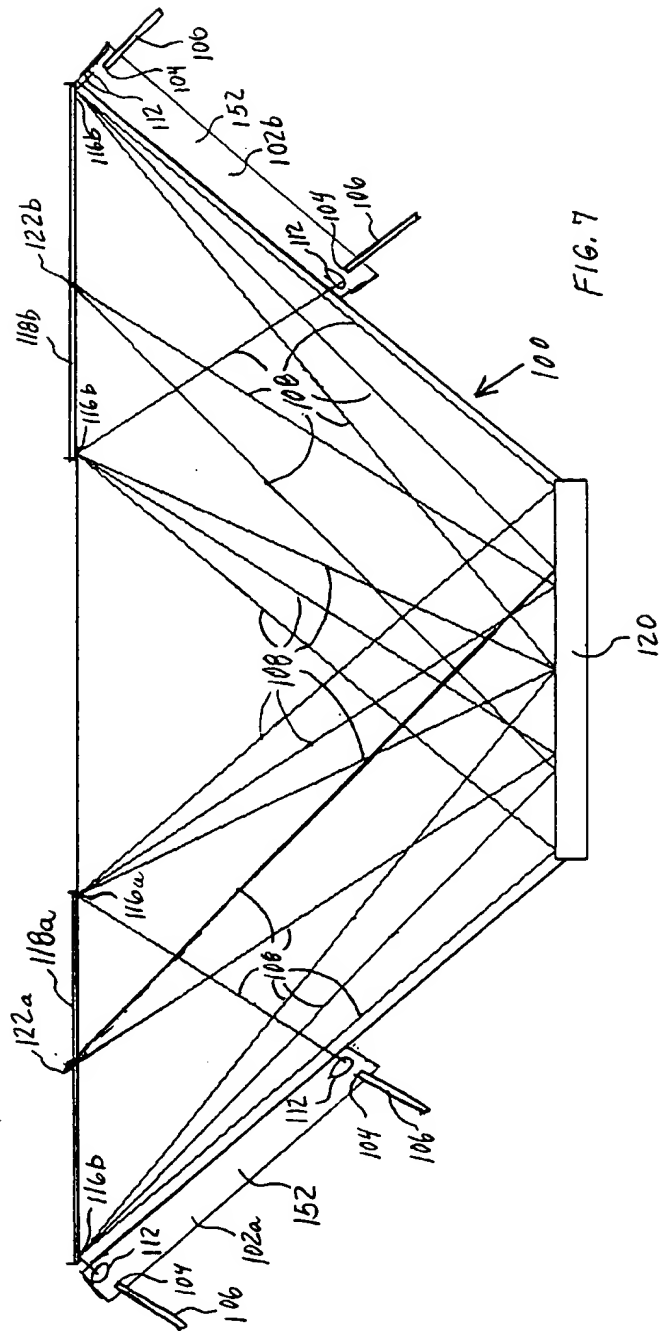


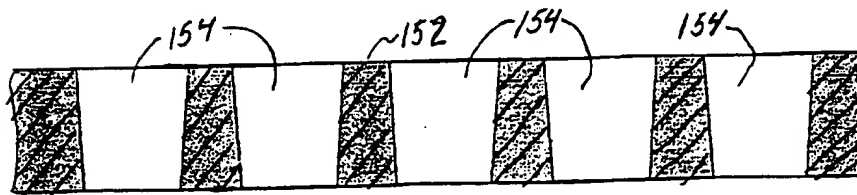
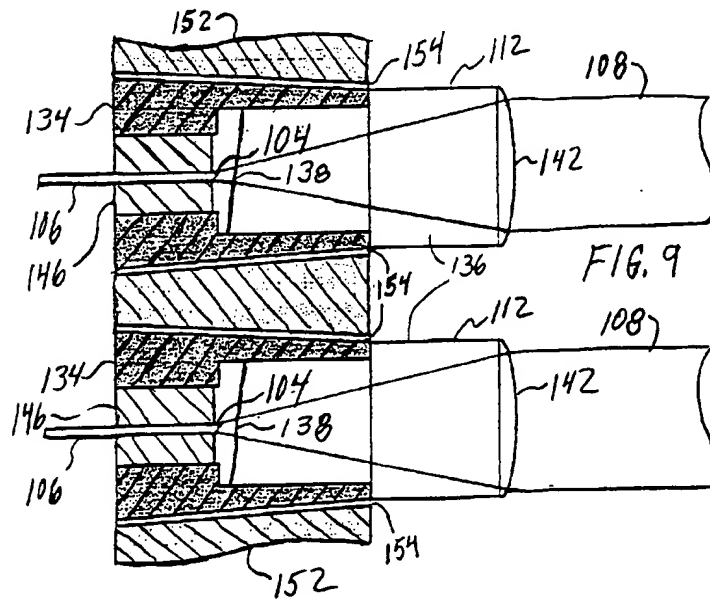
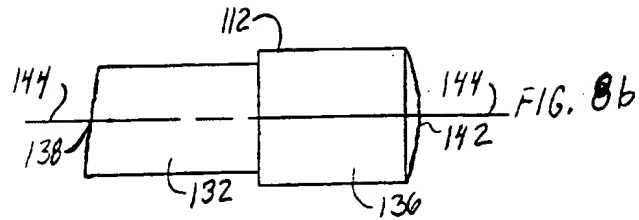
FIG. 4a

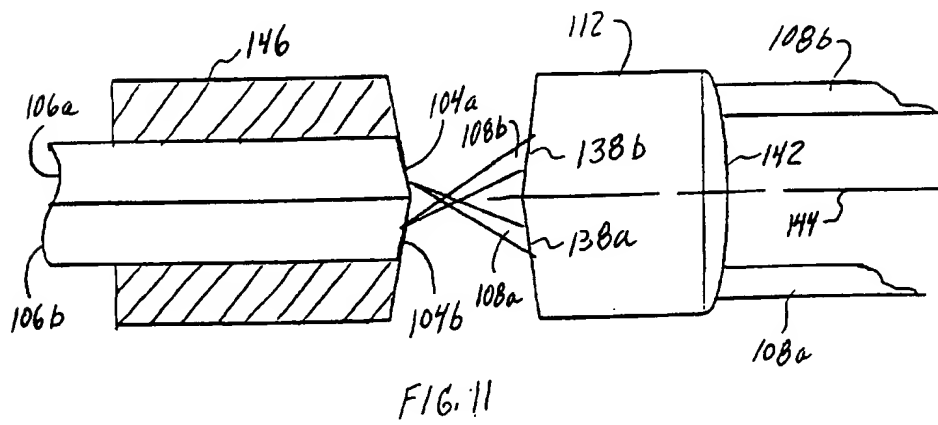
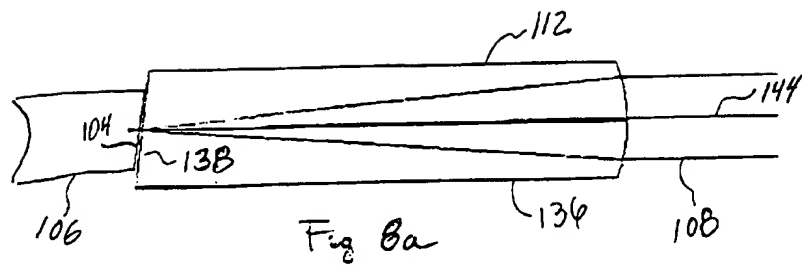


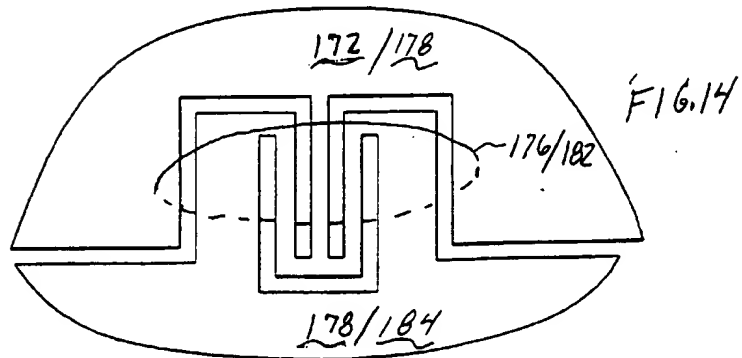
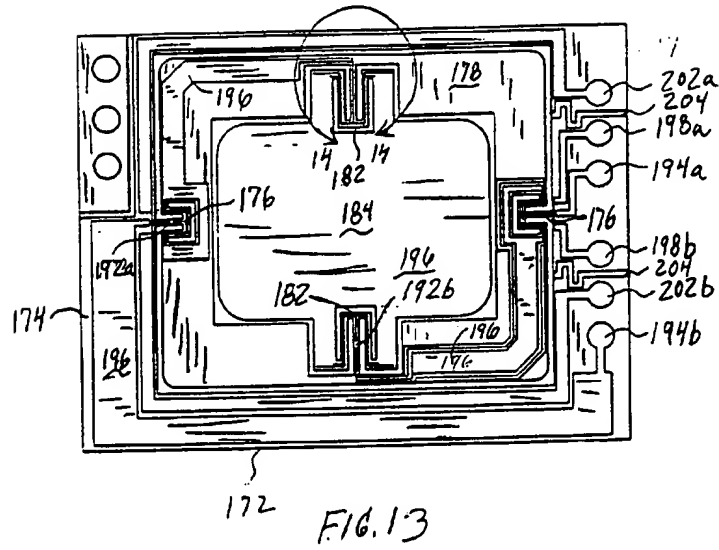
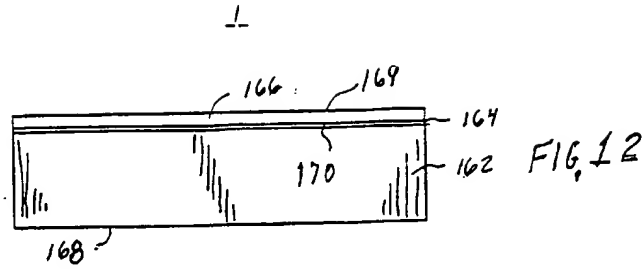




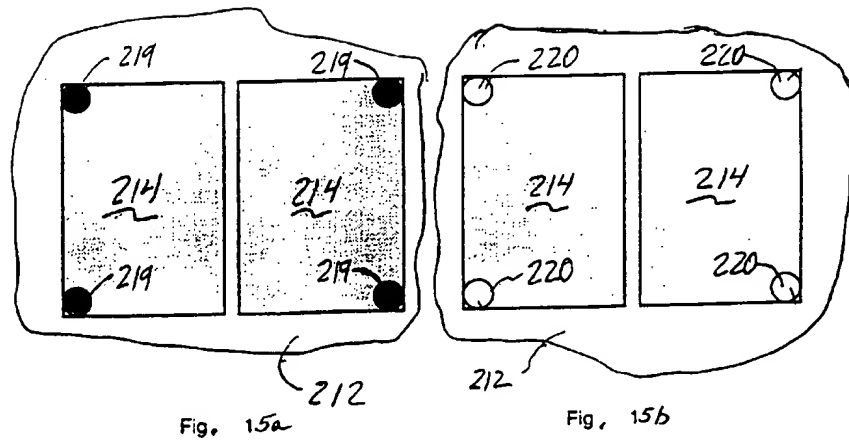
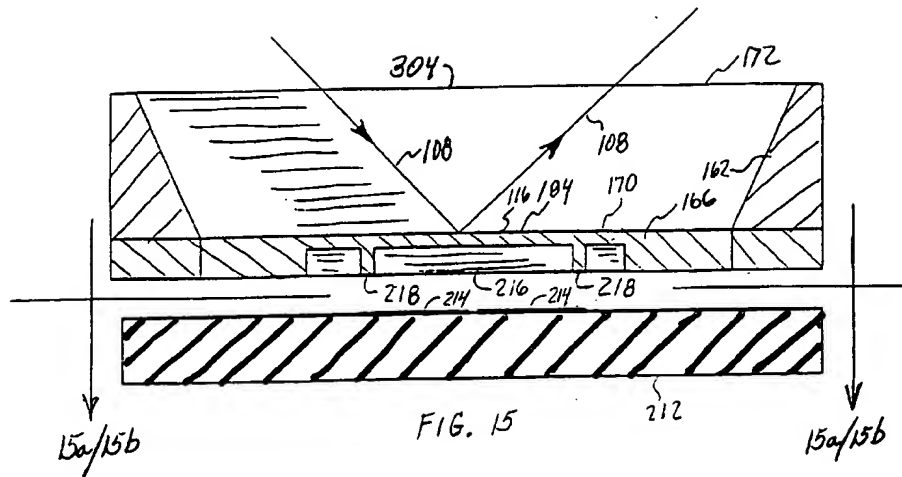
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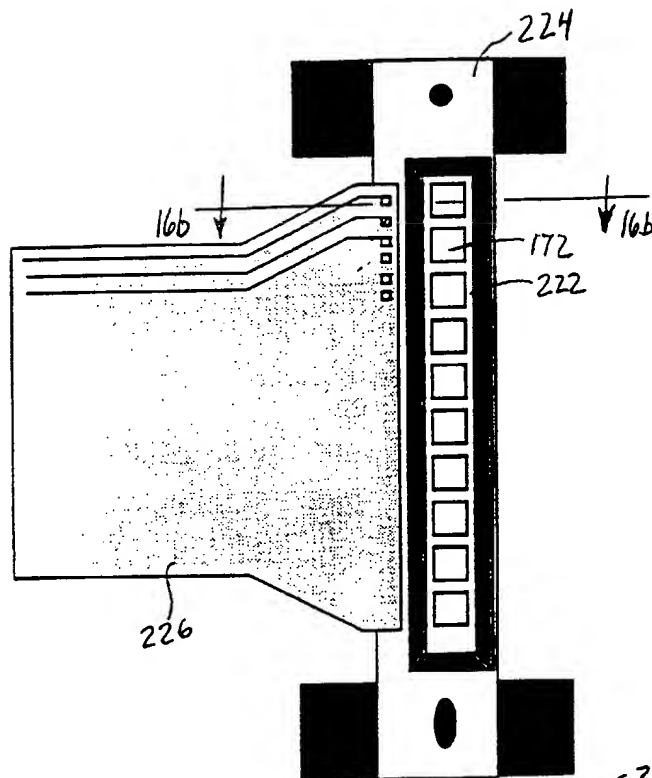


Fig. 16a

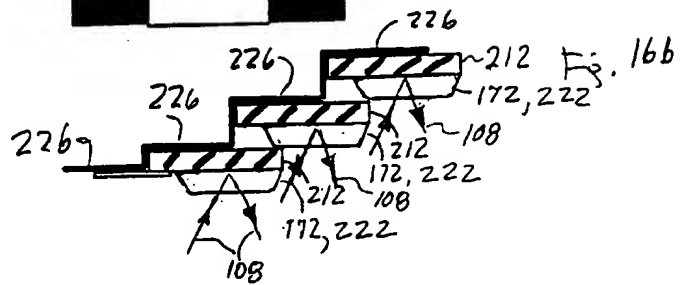
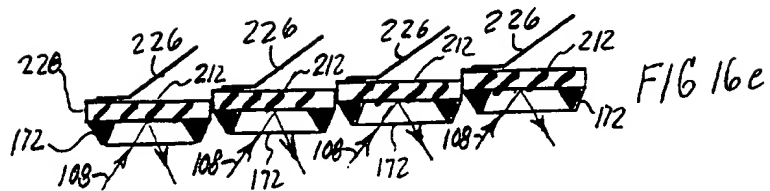
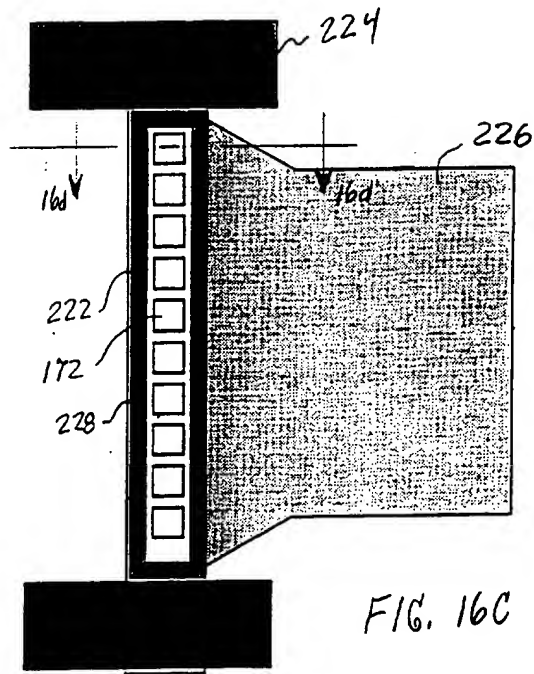
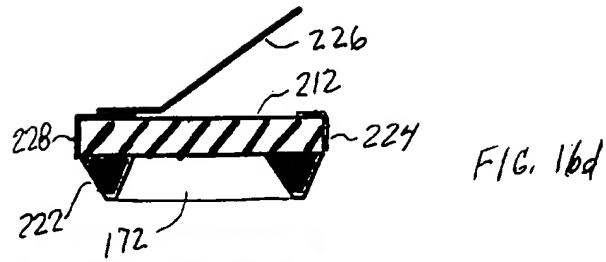
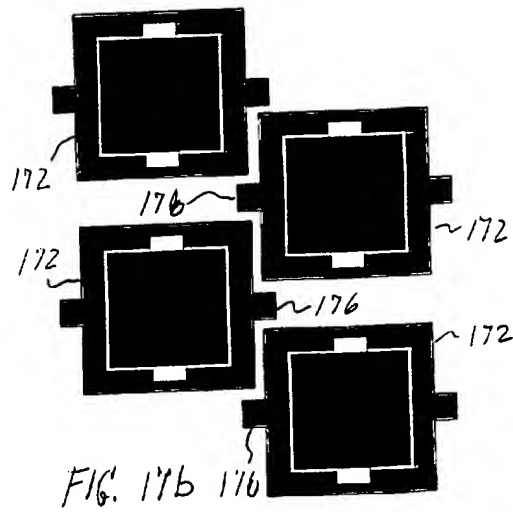
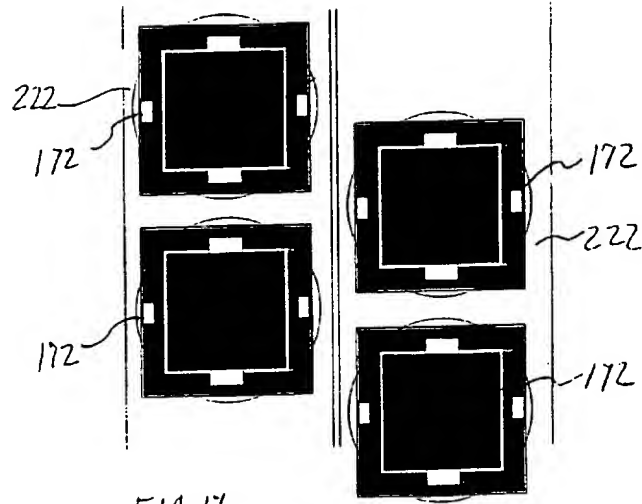
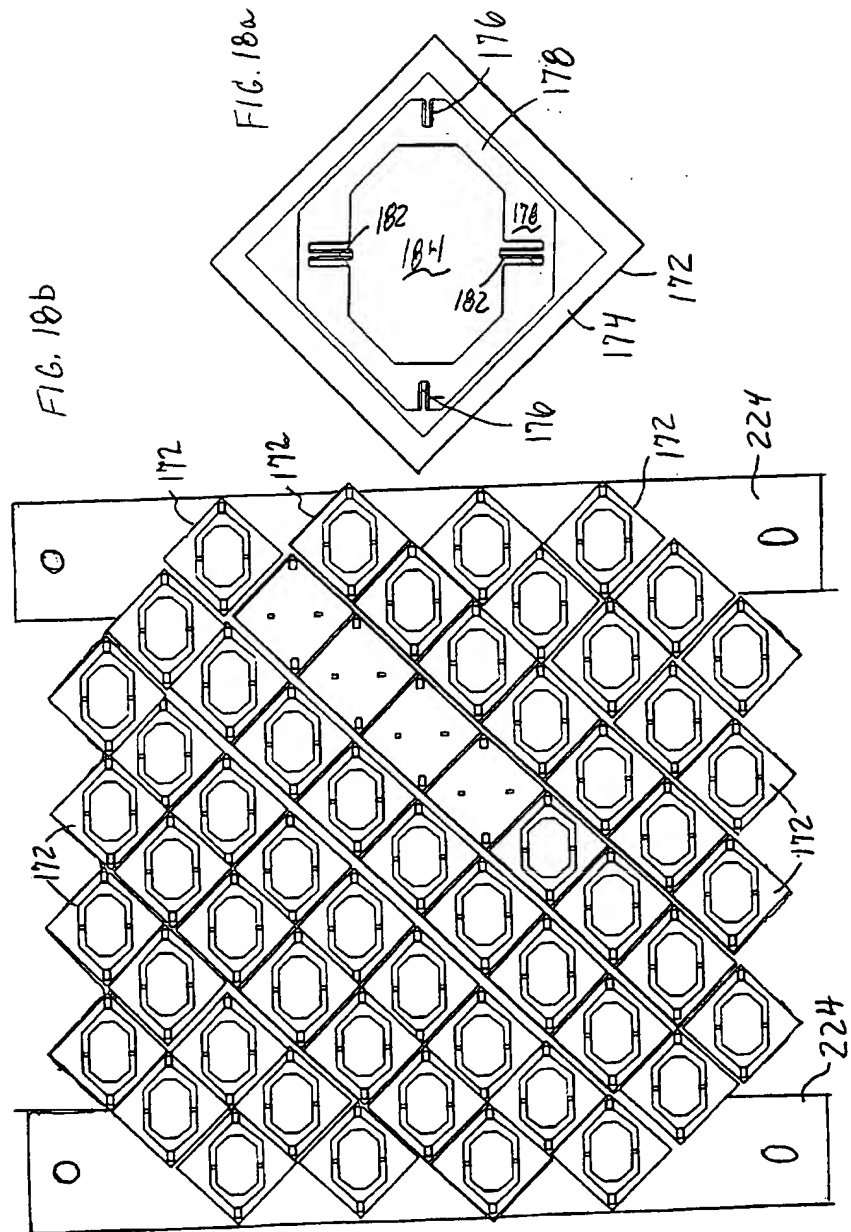


Fig. 16b

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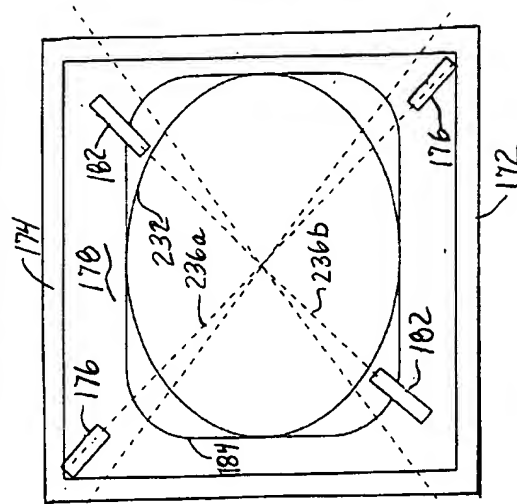


FIG. 19b

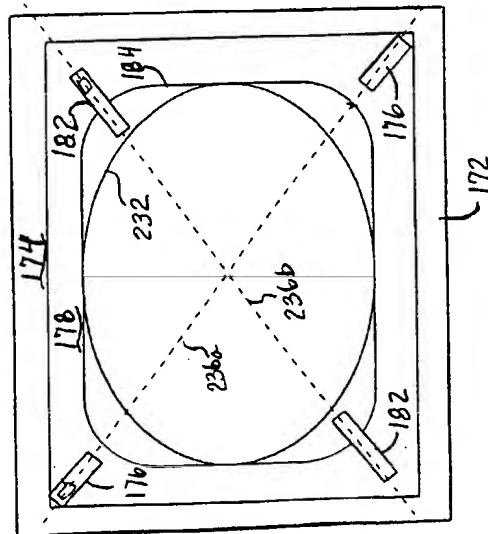


FIG. 19a

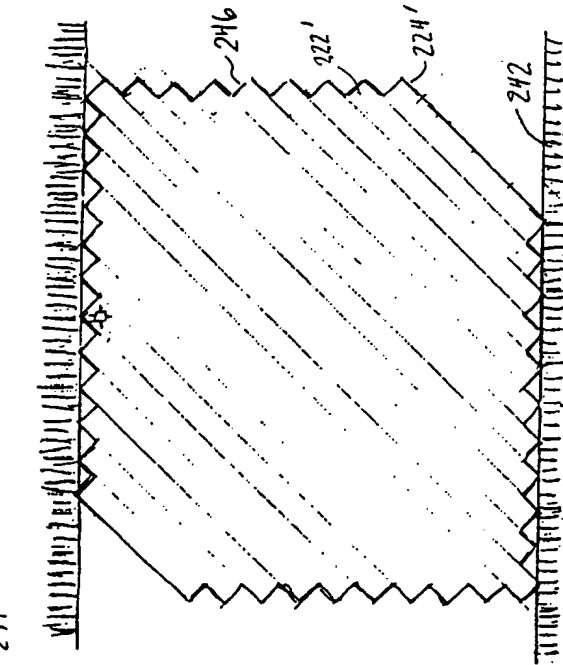
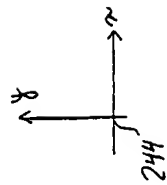


FIG. 20a

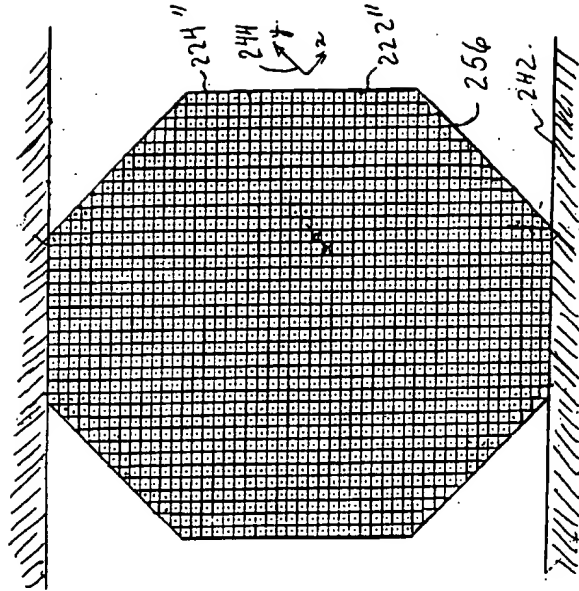


FIG. 20b

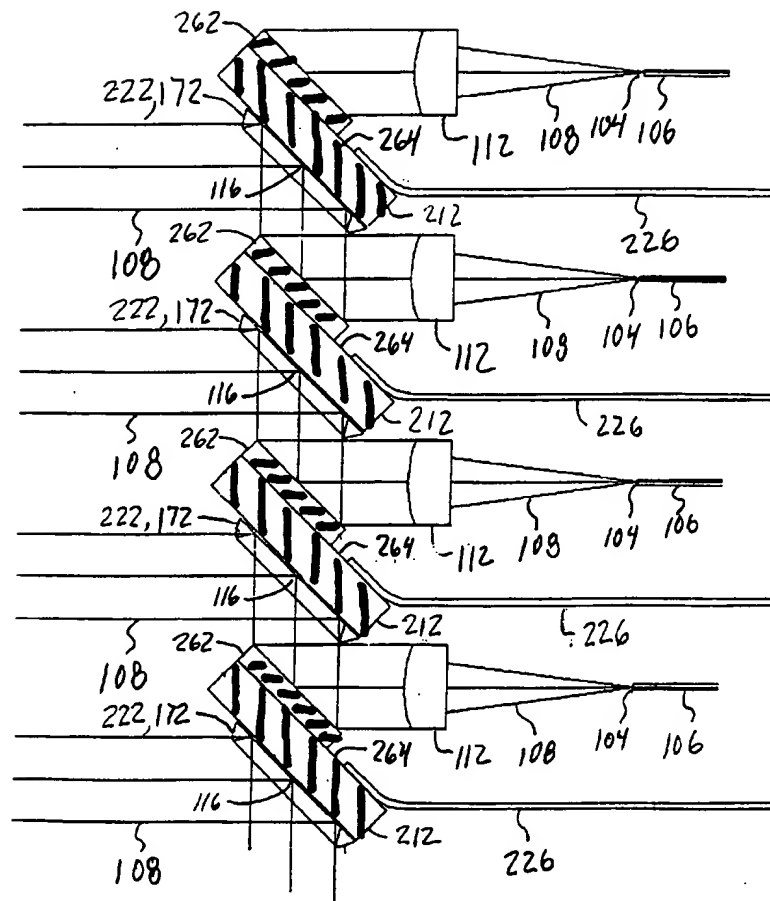
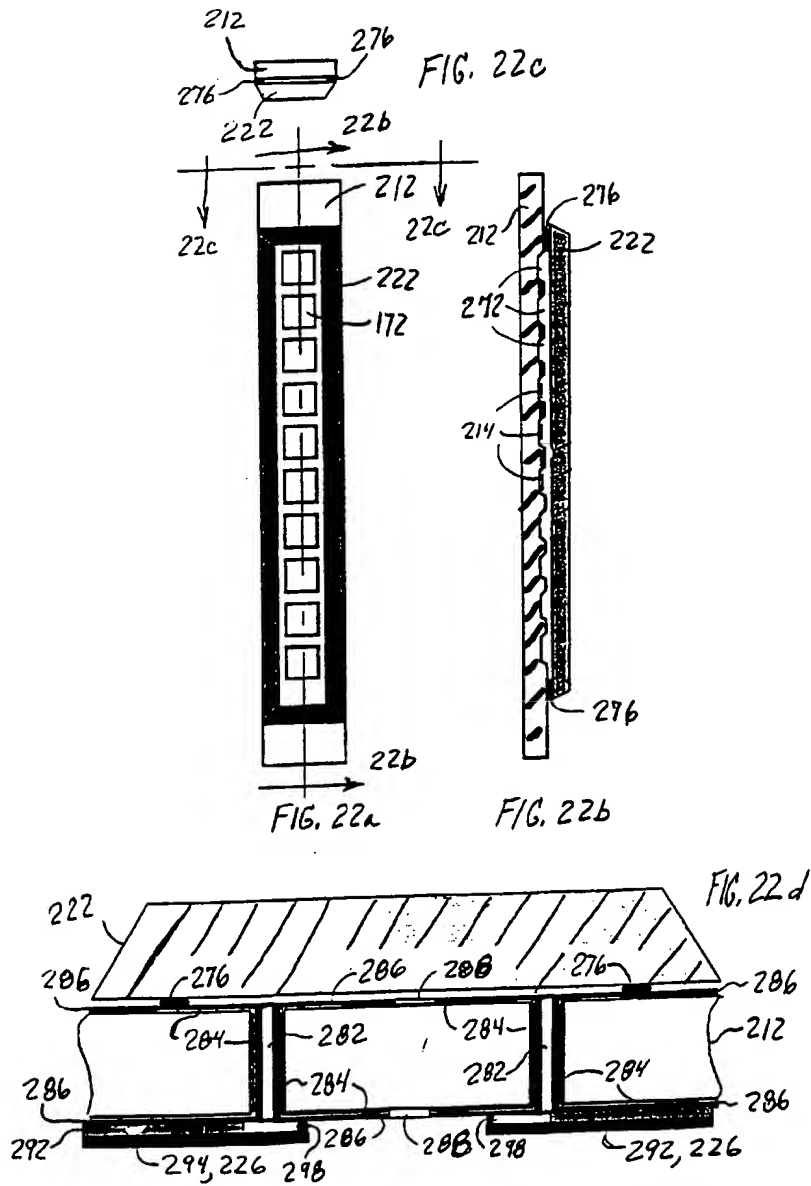


FIG. 21



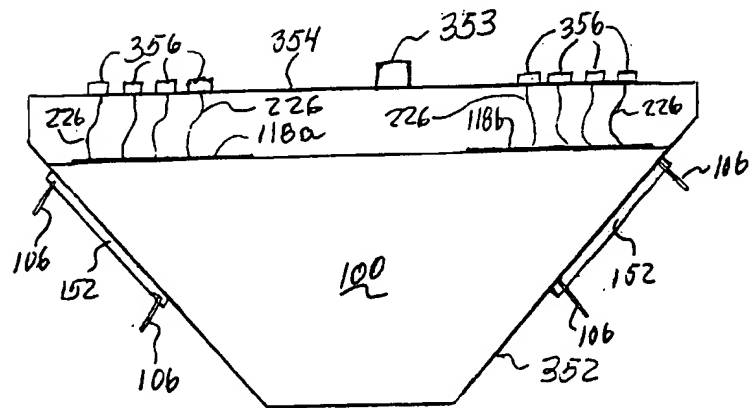
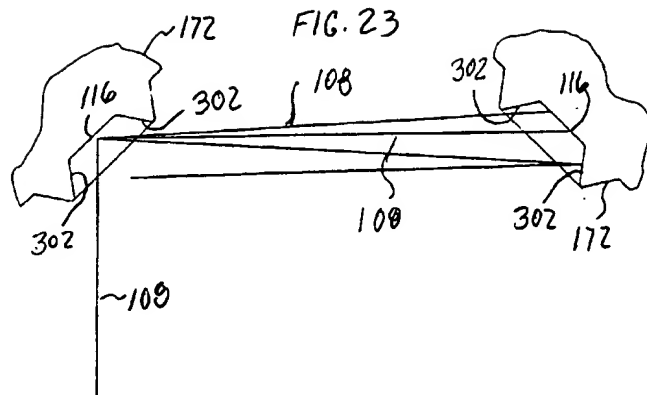
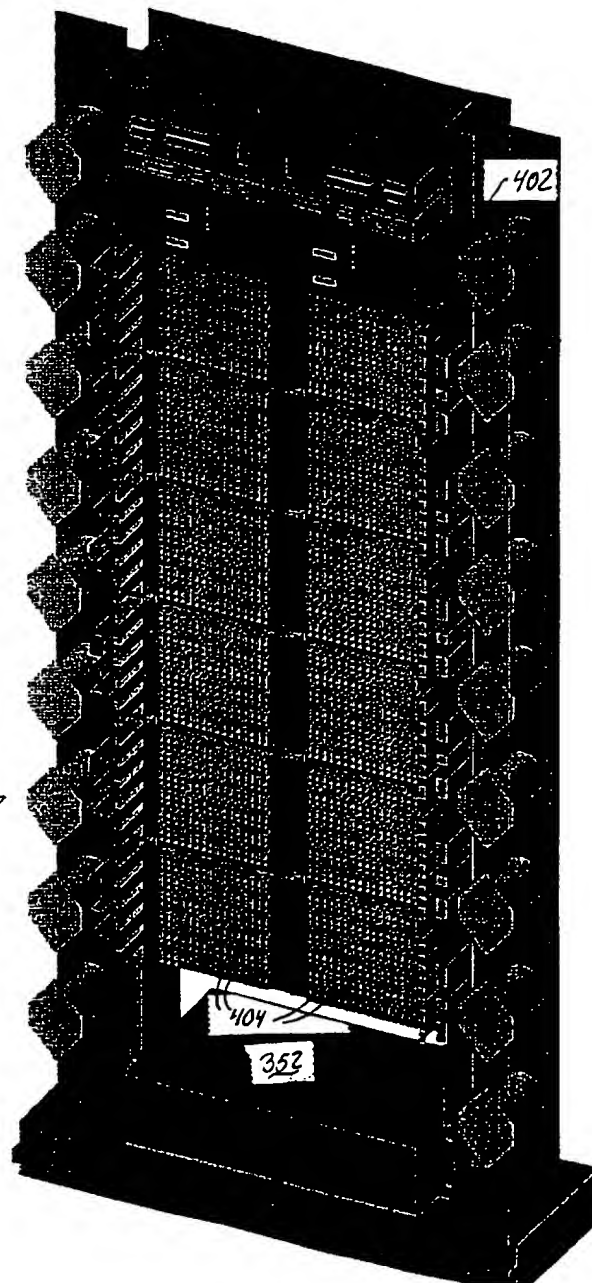
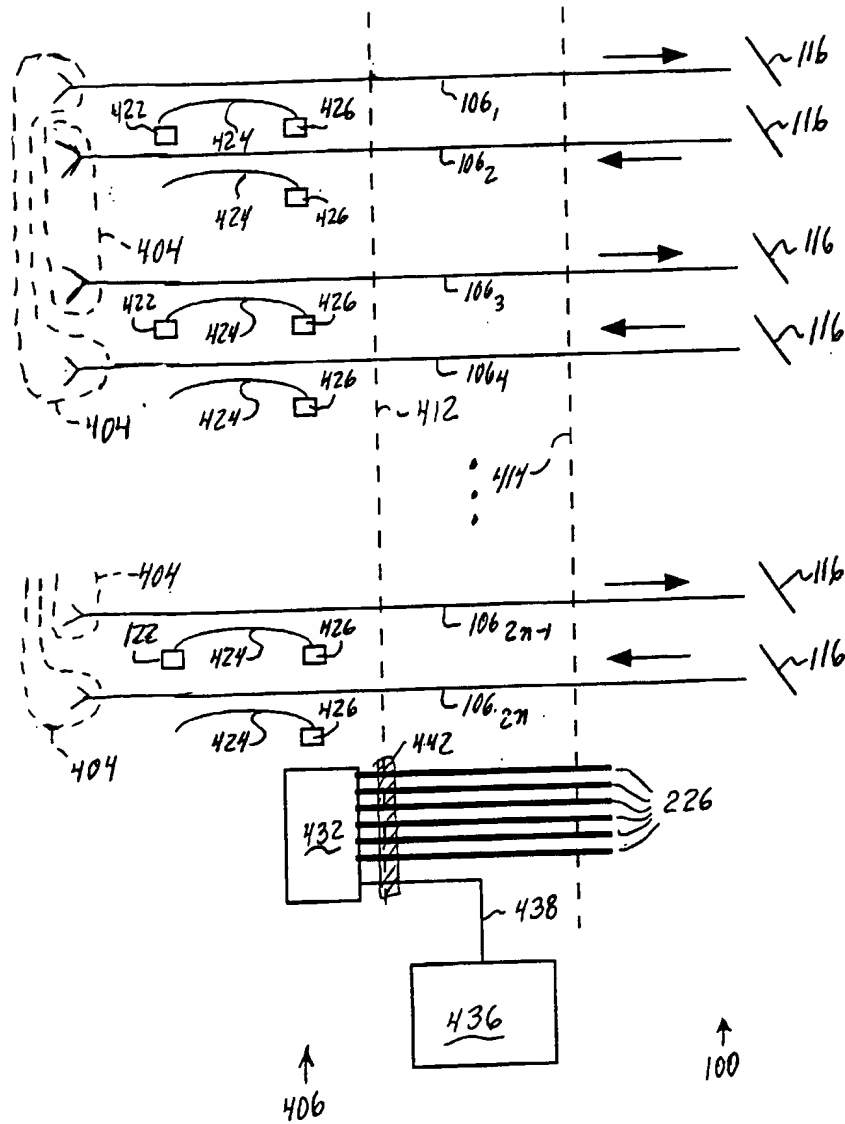


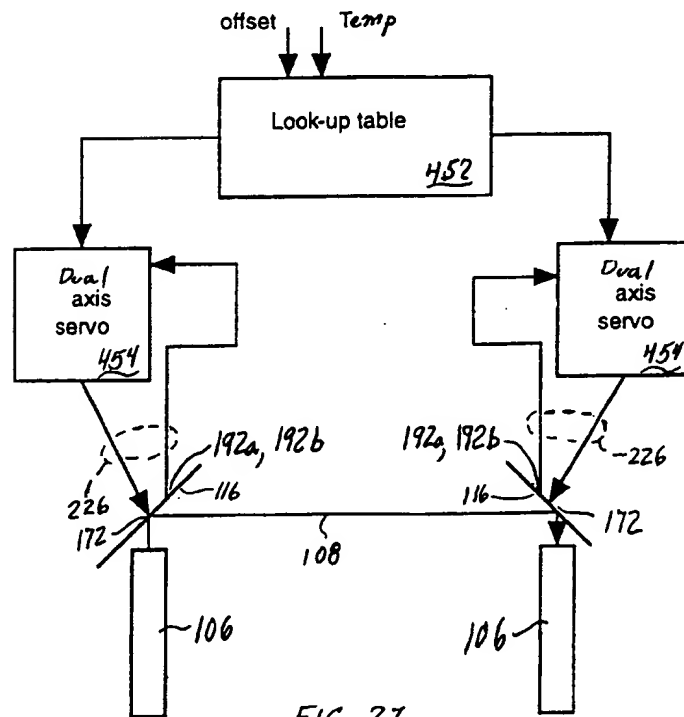
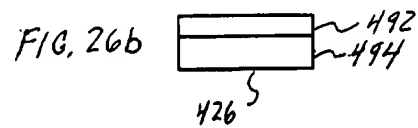
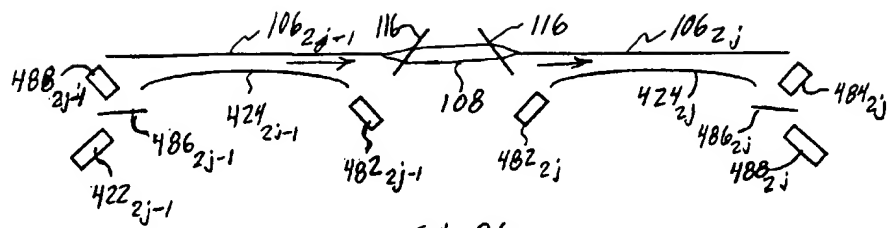
FIG. 24

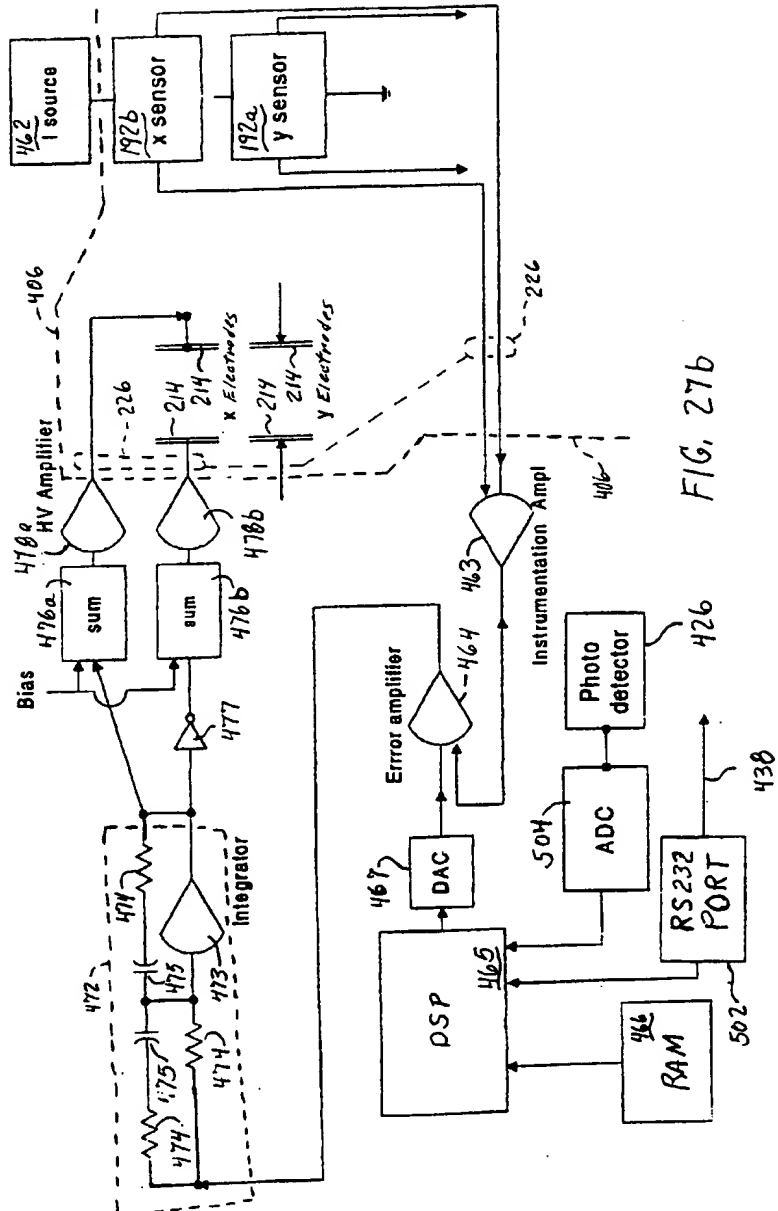
FIG. 25

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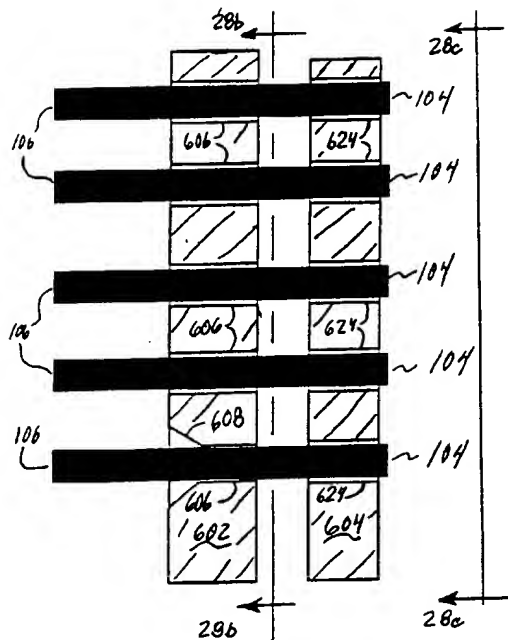


FIG. 20a

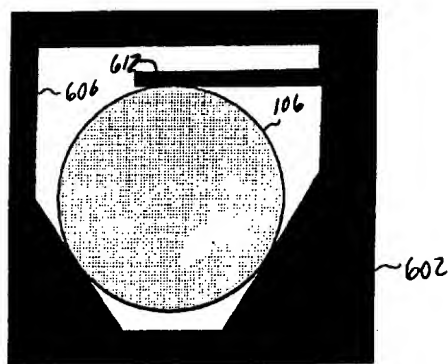


FIG 20b

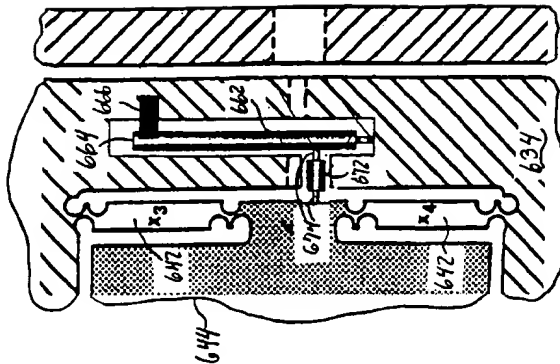


FIG. 29C

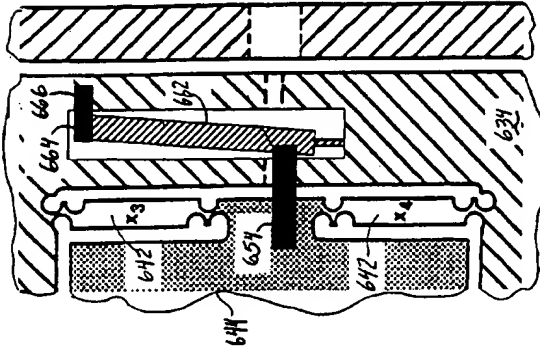


FIG. 29b

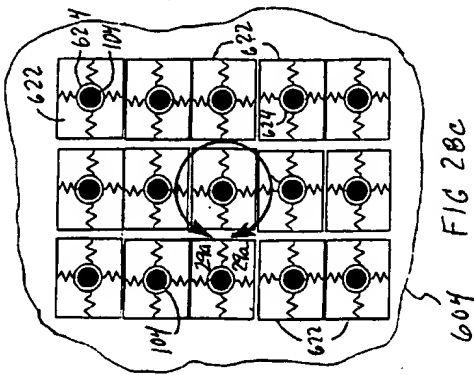
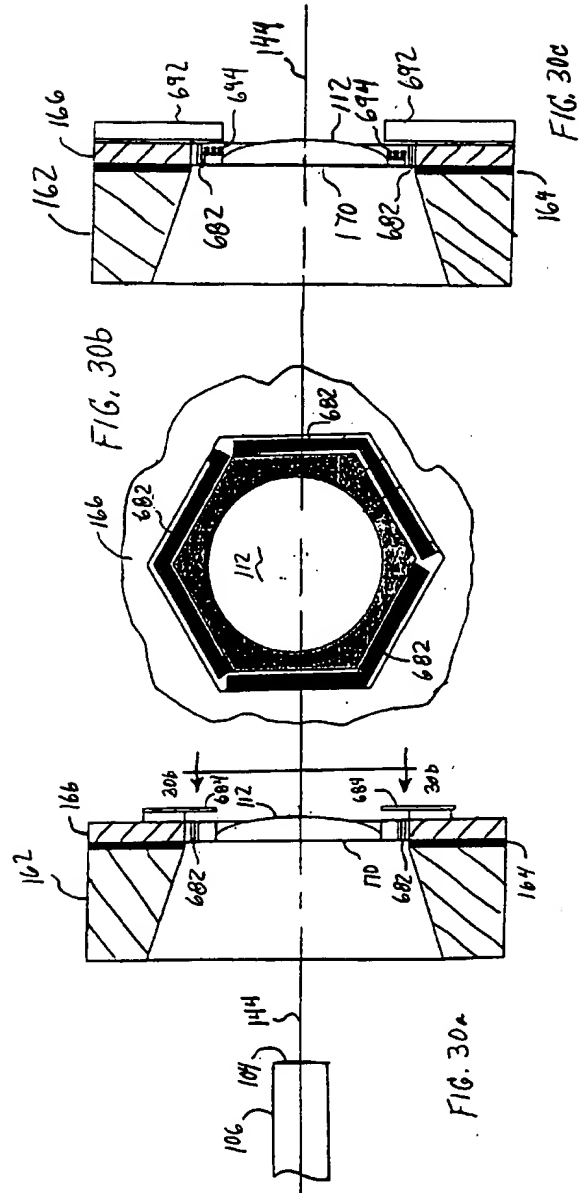


FIG 28c



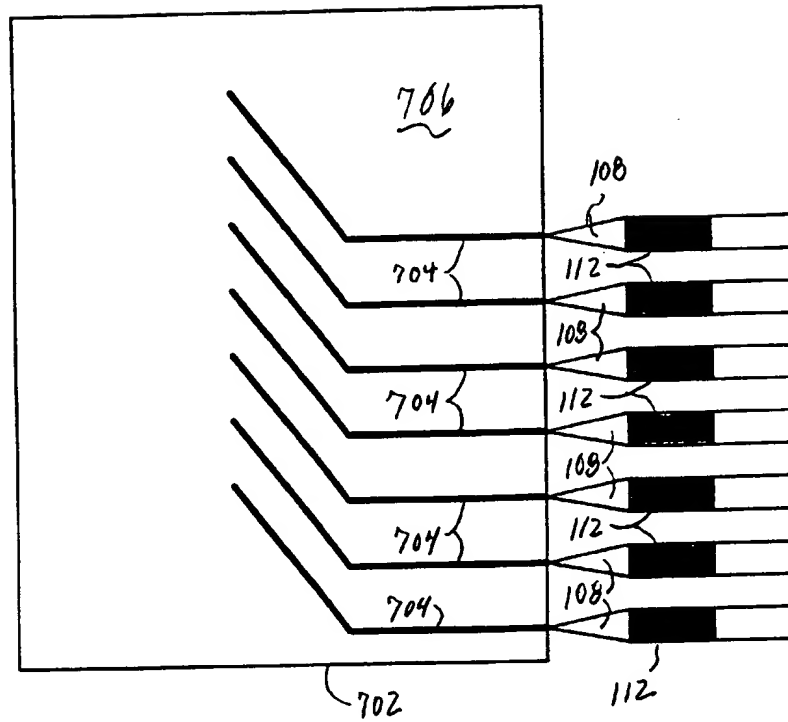


Fig. 31